

Forces and Motion

example 1: ball rolling on and falling off a table (again)

→ now math description of position-time graphs:

$$x(t) = c_1 t$$

with $c_1 = \text{const}$

$$y(t) = \begin{cases} h & \text{if } t \leq 0 \\ h - c_2 t^2 & \text{if } t \geq 0 \end{cases}$$

$$v_x = \frac{dx}{dt} = \frac{d}{dt}(c_1 t)$$

$$= c_1 \equiv v_{0,x}$$

$$v_y = \frac{dy}{dt} = \begin{cases} 0 & \text{if } t \leq 0 \\ -2c_2 t & \text{if } t \geq 0 \end{cases}$$

$$a_x = \frac{dv_x}{dt} = 0$$

$$a_y = \frac{dv_y}{dt} = \begin{cases} 0 & \text{if } t < 0 \\ -2c_2 = -g & \text{if } t > 0 \end{cases}$$

$$\hookrightarrow F_{x,\text{net}} = ma_x = 0$$

(note that we can't calculate a_y @ $t=0$)

$$\hookrightarrow F_{y,\text{net}} = ma_y = \begin{cases} 0 & \text{if } t < 0 \\ -mg & \text{if } t > 0 \end{cases}$$

We have used a few differential calculus rules:

$$\cdot \frac{d}{dt} (f(t) + g(t)) = \frac{df}{dt} + \frac{dg}{dt}$$

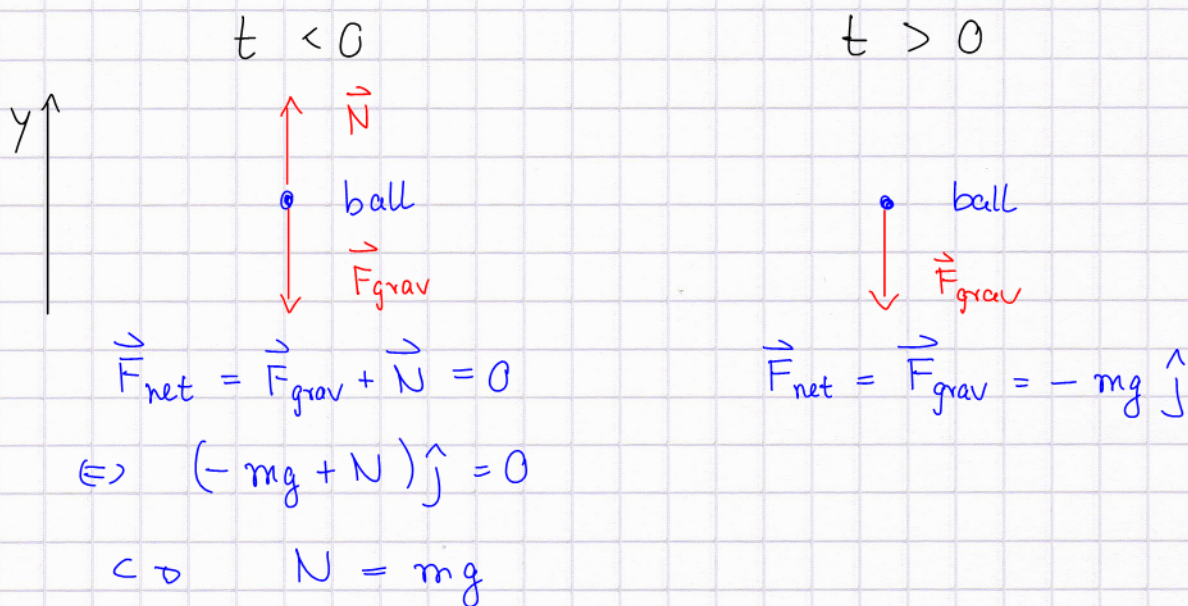
$$\cdot \frac{d}{dt} (\alpha f(t)) = \alpha \frac{df}{dt} \quad (\text{for any } \alpha \in \mathbb{R})$$

$$\cdot \frac{d}{dt} t^n = n t^{n-1}$$

Analysis

- $F_{x,\text{net}} = 0$ at all times: Newton-1 applies for horizontal motion (if frictionless)

- Gravity (weight) \vec{F}_{grav} acts in negative y direction
- \vec{F}_{grav} is compensated by normal force \vec{N} (due to table) at $t < 0$
- Free-body diagrams (FBDs)



- Horizontal and vertical motions are independent and can be analyzed separately.

example 2 : spacecraft in interstellar space

assume $\vec{F}_{\text{grav}} = 0$

case (i) : engine turned off \Rightarrow spacecraft is freely coasting on straight-line trajectory
 $\vec{r}(t) = \vec{r}_0 + \vec{v}_0 t$

case (ii) : engine turned on at $t = 0 \Rightarrow$ spacecraft is accelerating

assume $\vec{a} = a\hat{i}$ (for $t \geq 0$)

$\vec{v}_0 = \vec{v}(t=0) = v_0\hat{i}$

infer : $\vec{v}(t) = (v_0 + at) \hat{i}$

proof:
 $\frac{d\vec{v}}{dt} = a \hat{i} \quad \checkmark$

assume : $\vec{r}(t=0) = x_0 \hat{i}$

(educated) guess : $\vec{r}(t) = (x_0 + v_0 t + \frac{a}{2} t^2) \hat{i} = x(t) \hat{i}$

check , $\frac{d\vec{r}}{dt} = (v_0 + at) \hat{i} = \vec{v}(t) \quad \checkmark$

For 1D motion with constant acceleration one can easily derive a direct relation between x and v from the results given above:

$\Leftarrow \quad v = v_0 + at \quad \Leftrightarrow \quad t = \frac{v - v_0}{a}$

$x = x_0 + v_0 t + \frac{a}{2} t^2$

$= x_0 + v_0 \frac{v - v_0}{a} + \frac{a}{2} \left(\frac{v - v_0}{a} \right)^2$

$= x_0 + \frac{v_0 v}{a} - \frac{v_0^2}{a} + \frac{a}{2} \frac{(v - v_0)^2}{a^2}$

$= x_0 + \frac{1}{a} \left(\cancel{v_0 v} - v_0^2 + \frac{1}{2} (v^2 - 2\cancel{v_0 v} + v_0^2) \right)$

$= x_0 + \frac{v^2 - v_0^2}{2a}$

i.e. $x - x_0 = \frac{v^2 - v_0^2}{2a} \quad \Leftrightarrow \quad v^2 = v_0^2 + 2a(x - x_0)$

typical question that can be answered with this formula:

consider spacecraft with $v_0 = 100 \text{ m/s}$, $a = 20 \text{ m/s}^2$, $v_f = 400 \text{ m/s}$

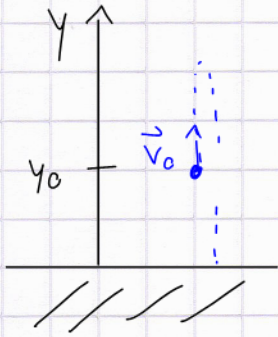
• distance travelled?

$d = x_f - x_0 = \frac{v_f^2 - v_0^2}{2a} = \frac{400^2 - 100^2 \text{ m}^2/\text{s}^2}{2 \cdot 20 \text{ m/s}^2} = 3.8 \text{ km}$

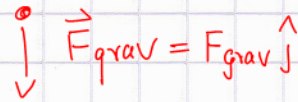
• how long did it take?

$v_f = v_0 + at_f \Leftrightarrow t_f = \frac{v_f - v_0}{a} = \frac{300 \text{ m/s}}{20 \text{ m/s}^2} = 15 \text{ s}$

example 3: free fall



FBD



Newton-2: $a_y = \frac{F_{grav}}{m} = \frac{-mg}{m} = -g$

$\Leftrightarrow v_y = v_0 - gt$

$\Leftrightarrow y = y_0 + v_0 t - \frac{g}{2} t^2$

$v_y^2 = v_0^2 - 2g(y - y_0)$

} see previous example with $a = -g$

typical questions and answers

- maximum height \rightarrow characterized by $v_y = 0$

$\Leftrightarrow v_y^2 = 0 = v_0^2 - 2g(y_{max} - y_0)$

$\Leftrightarrow y_{max} = y_0 + \frac{v_0^2}{2g}$

- how long does it take the ball to get there?

$v_y(t_{max}) = v_0 - gt_{max} \stackrel{!}{=} 0$

$\Leftrightarrow t_{max} = \frac{v_0}{g}$

- when does the ball hit the ground?

$y(t_{gr}) = y_0 + v_0 t_{gr} - \frac{g}{2} t_{gr}^2 \stackrel{!}{=} 0$

$\Leftrightarrow t_{gr}^2 - \frac{2v_0}{g} t_{gr} - \frac{2y_0}{g} = 0$

solve this quadratic equation for the special case $y_0 = 0$:

$t_{gr}^2 - \frac{2v_0}{g} t_{gr} = t_{gr} (t_{gr} - \frac{2v_0}{g}) = 0$

$\Leftrightarrow t_{gr} = \frac{2v_0}{g} = 2 t_{max}$

($t_{gr} = 0$ refers to initial situation)

- velocity @ t_{gr} : $v_y(t_{gr}) = v_0 - g t_{gr} = v_0 - 2v_0 = -v_0$