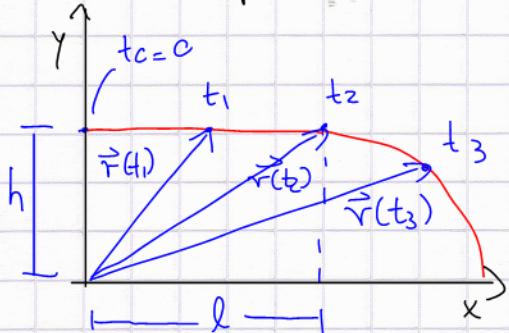


Motion := change of an object's position with time

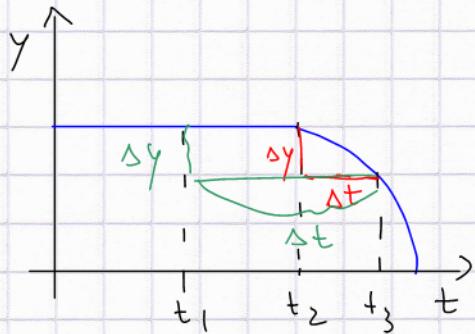
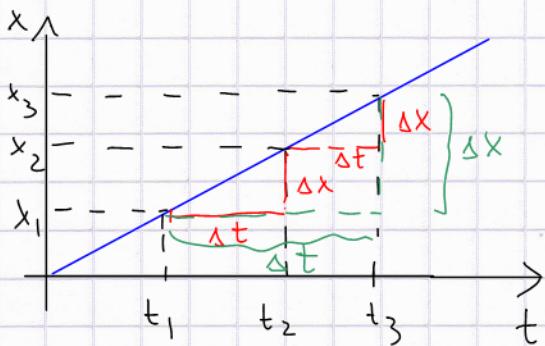
2D example: ball rolling on and falling off a table



motion is characterized by

$$\text{trajectory } \vec{r}(t) = x(t)\hat{i} + y(t)\hat{j}$$

position-time graphs (ignoring friction + air drag)



- introduce velocity $\vec{v} = v_x \hat{i} + v_y \hat{j}$ to characterize changes in object's position

$$v_x = \frac{\text{displacement}}{\text{time interval}} = \frac{\Delta x}{\Delta t}$$

$$\text{slope of } x-t \text{ graph} = \frac{x_2 - x_1}{t_2 - t_1} = \frac{x_3 - x_2}{t_3 - t_2}$$

$$= \frac{x_3 - x_1}{t_3 - t_1} = \text{const} > 0$$

$$v_y^{(2,1)} = \frac{y_2 - y_1}{t_2 - t_1} = 0$$

$$v_y^{(3,2)} = \frac{y_3 - y_2}{t_3 - t_2} < v_y^{(3,1)}$$

$$= \frac{y_3 - y_1}{t_3 - t_1} < 0$$

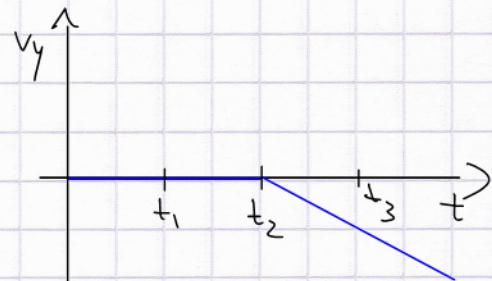
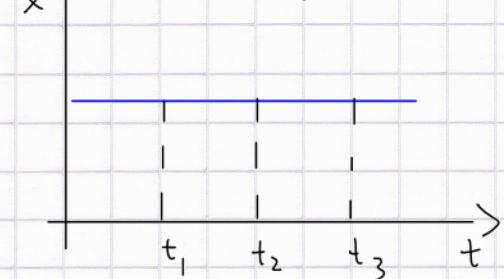
→ need instantaneous velocity for a complete characterization

$$v_x(t) = \lim_{\Delta t \rightarrow 0} \frac{\Delta x}{\Delta t} = \frac{dx}{dt} = \dot{x} \equiv x'(t)$$

$$v_y(t) = \lim_{\Delta t \rightarrow 0} \frac{\Delta y}{\Delta t} = \frac{dy}{dt} = \dot{y} \equiv y'(t)$$

different popular symbols for time-derivatives

v - t diagrams



instantaneous velocity vector:

$$\begin{aligned}\vec{v}(t) &= v_x(t) \hat{i} + v_y(t) \hat{j} = \frac{dx}{dt} \hat{i} + \frac{dy}{dt} \hat{j} \\ &= \frac{d}{dt} (x(t) \hat{i} + y(t) \hat{j}) = \frac{d}{dt} \vec{r}(t) = \frac{d\vec{r}}{dt} \\ &= \text{time derivative of position vector} \\ &= \text{slopes of position-time graphs at points } t\end{aligned}$$

• speed $v(t) = |\vec{v}(t)| = \sqrt{v_x^2(t) + v_y^2(t)} \geq 0$

• average velocity $\vec{V}_{ave} = \frac{\Delta \vec{r}}{\Delta t} = \frac{\Delta x}{\Delta t} \hat{i} + \frac{\Delta y}{\Delta t} \hat{j}$
(wrt given time interval)

Summary: 2D motion is characterized by

- trajectory

$$\vec{r}(t) = x(t) \hat{i} + y(t) \hat{j}$$

- velocity

$$\vec{v}(t) = \frac{d}{dt} \vec{r}(t)$$

- acceleration

$$\vec{a}(t) = \frac{d}{dt} \vec{v}(t) = \frac{d^2}{dt^2} \vec{r}(t)$$

i.e. $a_x(t) = \dot{v}_x = \ddot{x}$, $a_y(t) = \dot{v}_y = \ddot{y}$ second derivative

study of motion:
"kinematics"