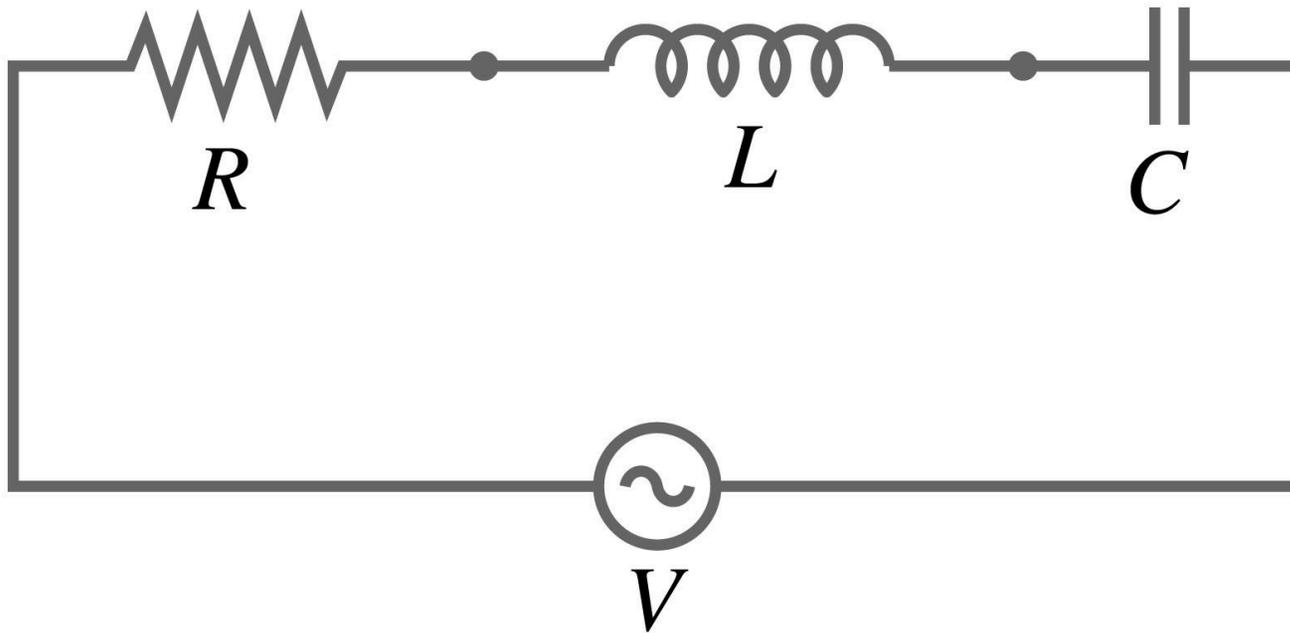


Biophysics I (BPHS 3090)

Instructors: Prof. Christopher Bergevin (cberge@yorku.ca)

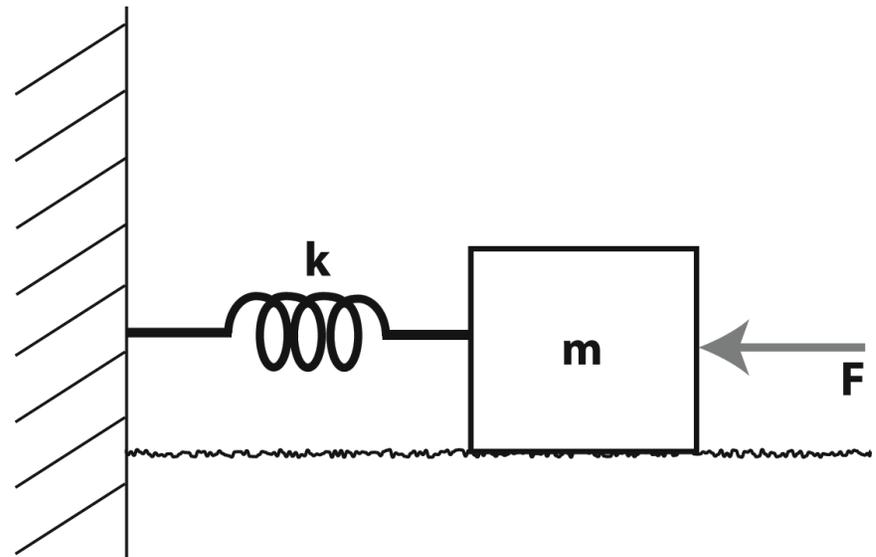
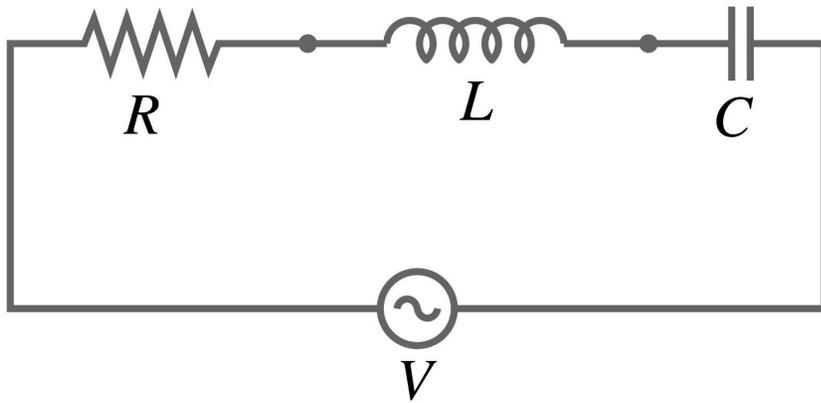
Website: <http://www.yorku.ca/cberge/3090W2015.html>

RLC Circuits as an example



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RLC circuit = Damped, Driven Harmonic Oscillator



Case 1: Undamped, Undriven

$$F = ma = m\ddot{x} = -kx$$

Newton's Second Law
Hooke's Law

$$\ddot{x} + \frac{k}{m}x = 0$$

Second order differential
equation

$$x(t) = A \cos(\omega_o t + \phi)$$

⇒ Solution is oscillatory!

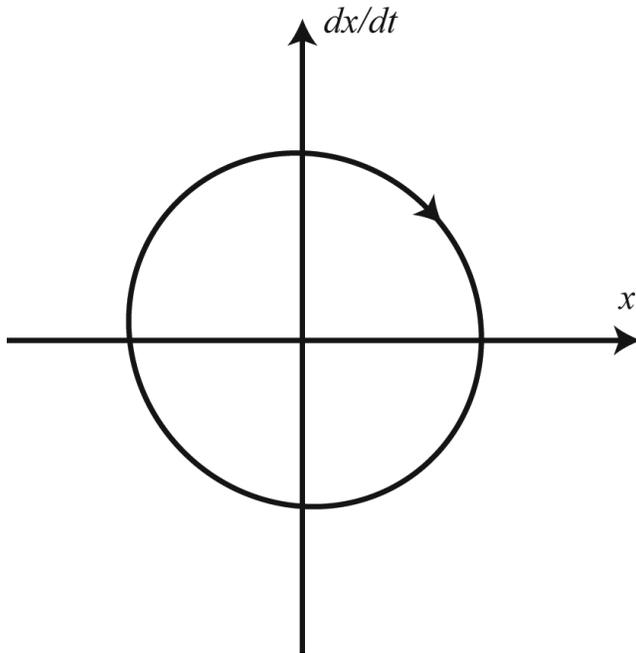
$$\omega_o = \sqrt{k/m}$$

System has a
natural frequency

Case 1: Undamped, Undriven (cont.)

Consider the system's energy:

$$E = T + U = \frac{1}{2}m\dot{x}^2 + \frac{1}{2}kx^2$$



phase plane portrait for H.O.

- Two means to *store* energy: mass and spring
- Oscillation results as energy transfers back and forth between these two *modes* (i.e., system is considered second-order)

Case 2: Undamped, Driven

$$\ddot{x} + \frac{k}{m}x = F_o \cos \omega t$$

Sinusoidal driving force at frequency ω

Assumption: Ignore onset behavior and that system oscillates at frequency ω

$$x(t) = B \cos(\omega t + \alpha)$$

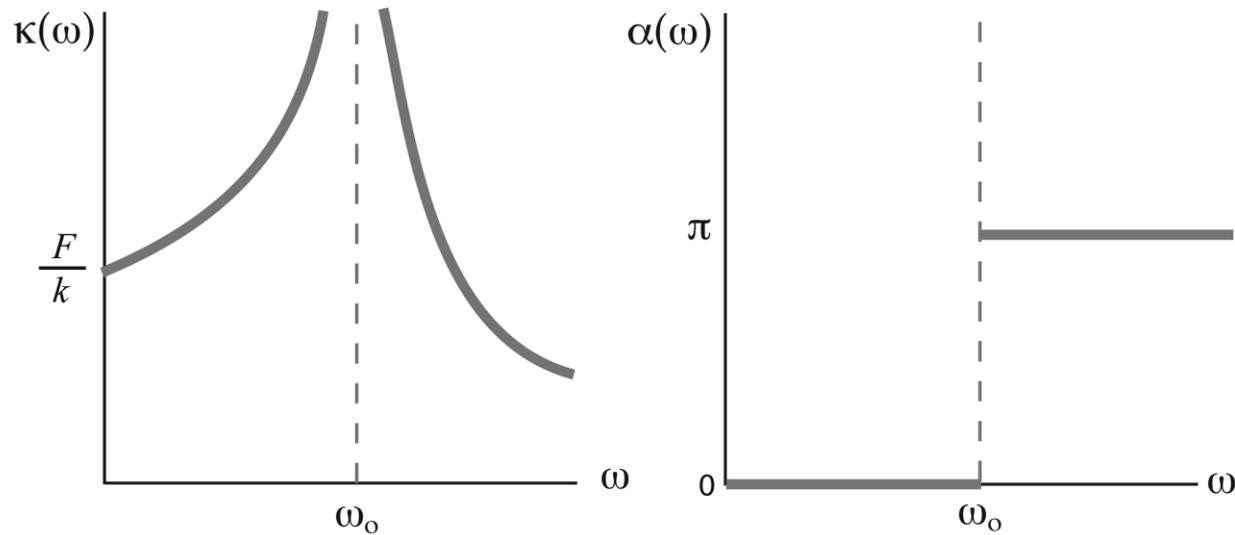
Assumed form of solution

$$-m\omega^2 B \cos \omega t + kB \cos \omega t = F_o \cos \omega t$$

$$x(t) = \frac{F_o/m}{\omega_o^2 - \omega^2} \cos(\omega t + \alpha)$$

Case 2: Undamped, Driven (cont.)

$$x(t) = \frac{F_o/m}{\omega_o^2 - \omega^2} \cos(\omega t + \alpha) = \kappa(\omega) \cos(\omega t + \alpha)$$



Two Important Concepts Demonstrated Here:

- **Resonance** when system is driven at natural frequency
- **Phase shift** of 1/2 cycle about resonant frequency

Case 3: Damped, Undriven

$$m\ddot{x} + b\dot{x} + kx = 0$$

Purely sinusoidal solution
no longer works!

$$\ddot{x} + \gamma\dot{x} + \omega_o^2 x = 0$$

Change variables

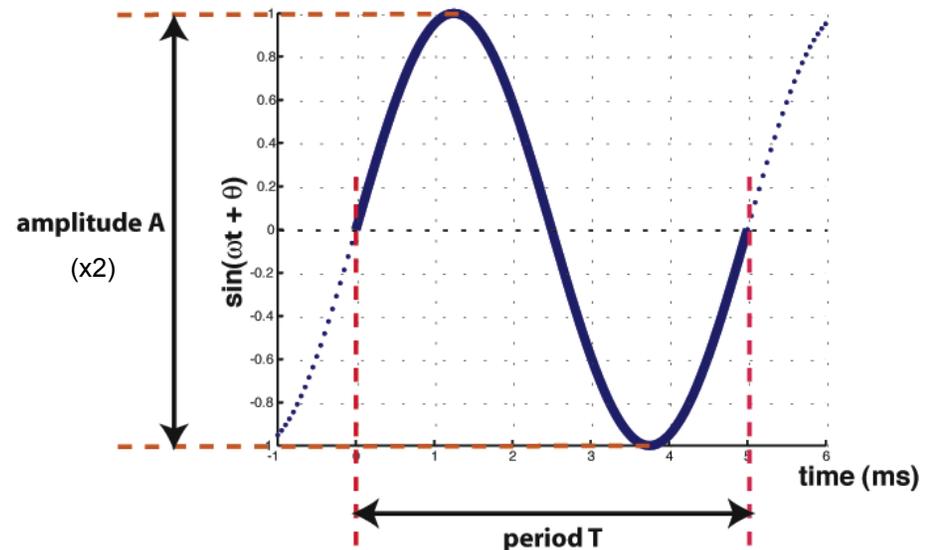
Assumption: Form of solution is a
complex exponential

$$x(t) = Ae^{i(\omega t + \delta)}$$

Trigonometry review \Rightarrow Sinusoids

Sinusoid has 3 basic properties:

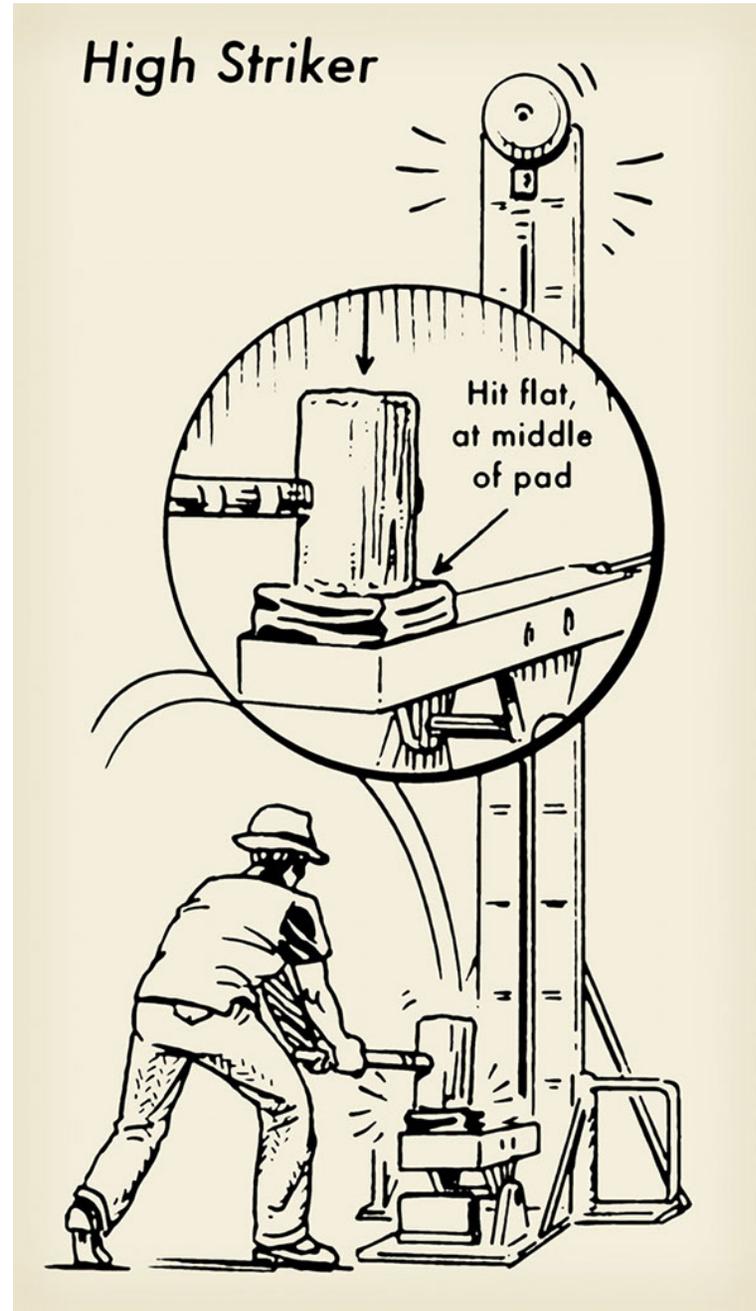
- i. **Amplitude** - height
- ii. **Frequency** = $1/T$ [Hz]
- iii. **Phase** - tells you where the peak is (needs a reference)



\Rightarrow Phase reveals timing information

Magnitude

→ 'Size' is key here



Phase

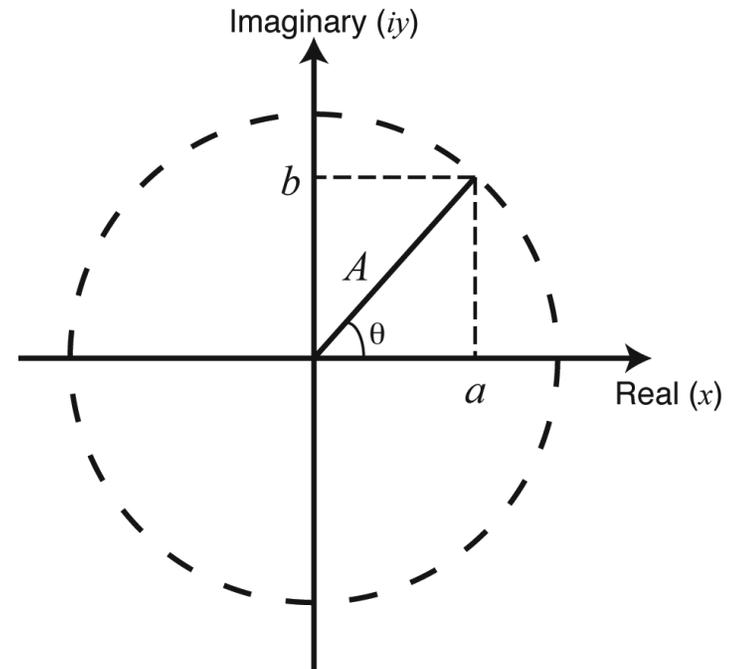


→ 'Timing' is key here
(on a cycle-by-cycle basis)

Case 3: Damped, Undriven (cont.)

Motivation for complex solution:

$$\begin{aligned} a + ib &= Ae^{i\theta} \\ &= A(\cos \theta + i \sin \theta) \end{aligned}$$



Cartesian Form

$$a = A \cos(\theta)$$

$$b = A \sin(\theta)$$

Polar Form

$$A = \sqrt{a^2 + b^2}$$

$$\theta = \tan^{-1} \left(\frac{b}{a} \right)$$



\Rightarrow Complex solution contain both magnitude and phase information

Case 3: Damped, Undriven

$$\ddot{x} + \gamma\dot{x} + \omega_o^2 x = 0$$

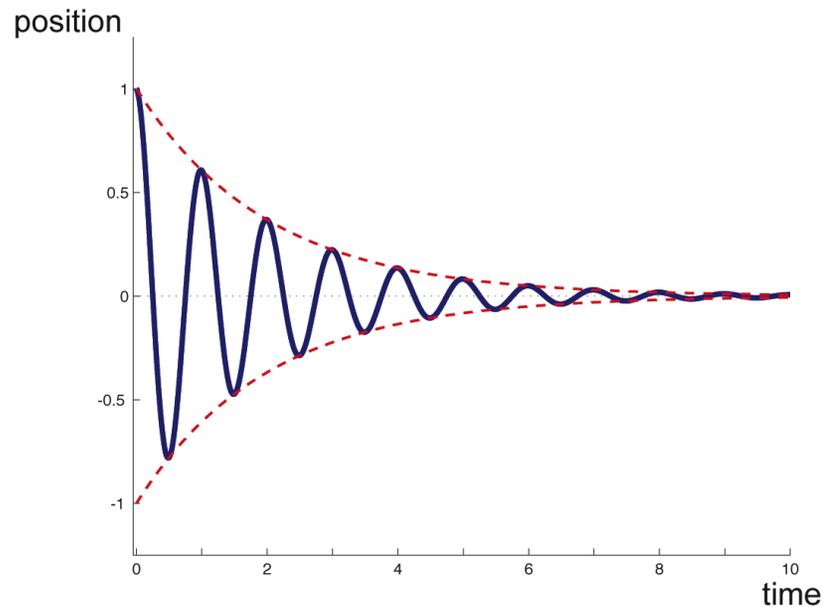
$$x(t) = Ae^{i(\omega t + \delta)}$$

$$x(t) = Ae^{-\gamma t/2} e^{i(\omega t + \alpha)}$$

$$\omega^2 = \omega_o^2 - \frac{\gamma^2}{4}$$

(slightly lower frequency of oscillation due to damping)

[A and α are constants of integration, depending upon initial conditions]



⇒ Damping causes energy loss from system

Case 4: Damped, Driven

$$\ddot{x} + \gamma\dot{x} + \omega_o^2 x = \frac{F_o}{m} e^{i\omega t}$$

Sinusoidal driving force at frequency ω

Assumption: Ignore onset behavior and that system oscillates at frequency ω

$$x(t) = Ae^{-i(\omega t + \delta)}$$

Assumed form of solution

$$A(\omega) = \frac{F_o/m}{[(\omega_o^2 - \omega^2)^2 + (\gamma\omega)^2]^{1/2}}$$

(magnitude)

$$\delta(\omega) = \arctan\left(\frac{\gamma\omega}{\omega^2 - \omega_o^2}\right)$$

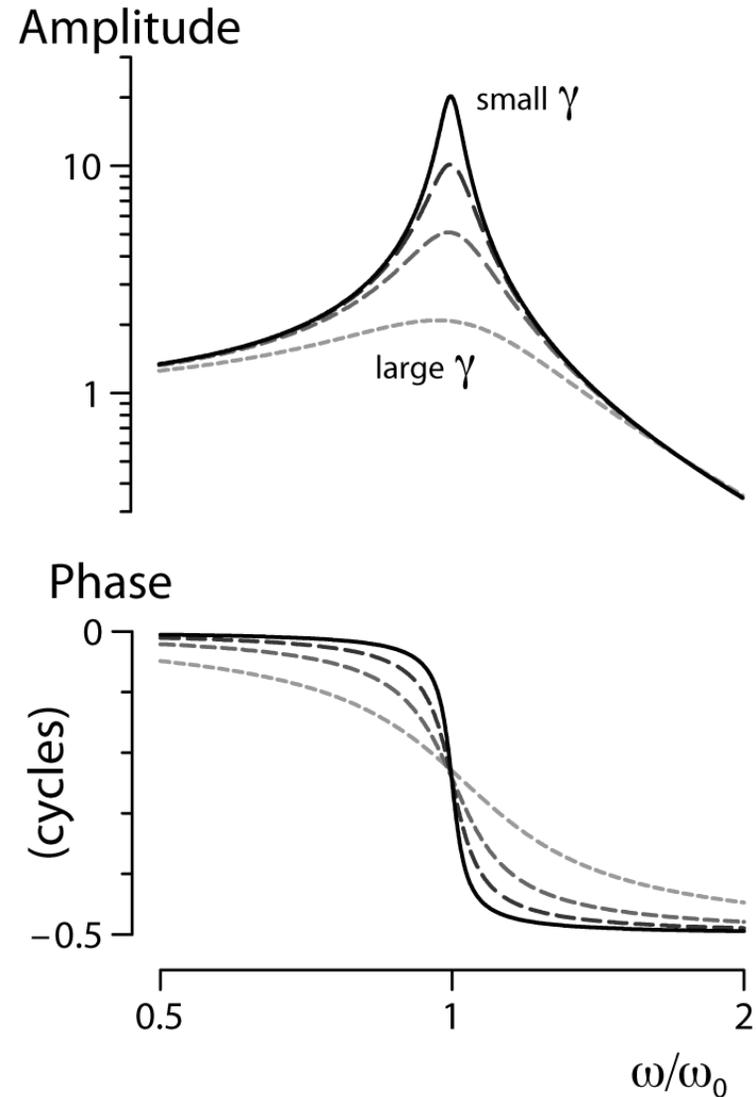
(phase)

Case 4: Damped, Driven (cont.)

$$A(\omega) = \frac{F_o/m}{[(\omega_o^2 - \omega^2)^2 + (\gamma\omega)^2]^{1/2}}$$

$$\delta(\omega) = \arctan\left(\frac{\gamma\omega}{\omega^2 - \omega_o^2}\right)$$

⇒ Second-order oscillator behaves as
as *band-pass filter*
(i.e., it is a mechanical Fourier transformer
tuned to a specific frequency)



Case 4: Damped, Driven (cont.)

- Can find general solution (e.g., transient behavior at onset) by considering a particular solution and the solution to the homogeneous equation

- Quality Factor (Q):

$$Q = \frac{\omega_o}{\gamma}$$

Reveals how sharply tuned the system is (i.e., ability to resolve different frequencies)

⇒ Sharply tuned oscillators have long *build-up* times

- Impedance (Z):

$$Z \equiv \frac{F_{ext}}{\dot{x}} = \frac{x \cdot (-m\omega^2 + k + i\omega b)}{x \cdot i\omega} = b + i \left[m\omega - \frac{k}{\omega} \right]$$

⇒ Real part of Z (*resistance*) describes energy loss while imaginary part (*reactance*) describes energy storage

RLC circuit = Damped, Driven Harmonic Oscillator

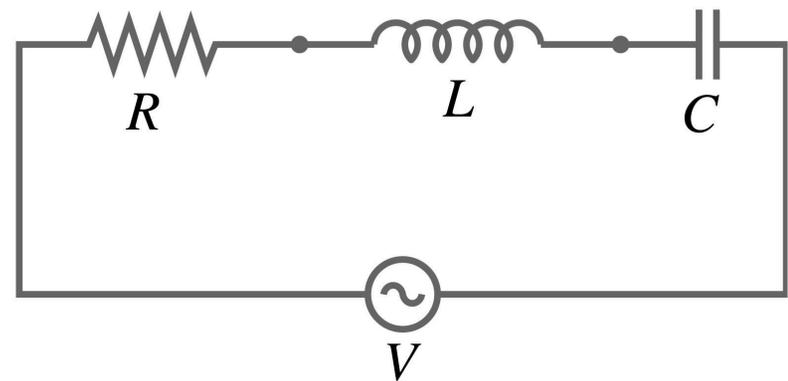
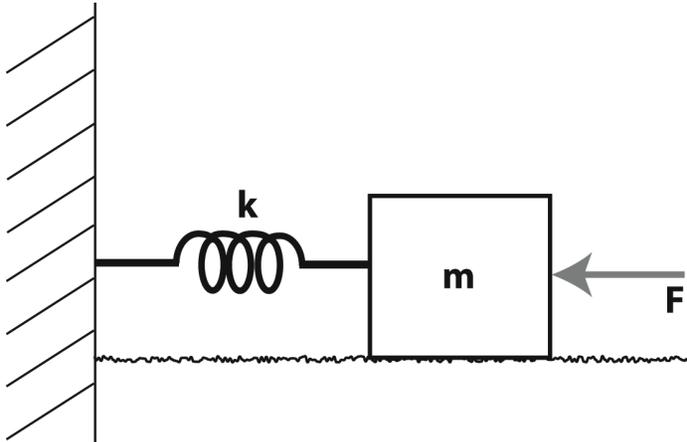
Mechanical

F (force) \leftrightarrow
 v (velocity) \leftrightarrow
 x (position) \leftrightarrow
 m (mass) \leftrightarrow
 b (damping) \leftrightarrow
 k (spring) \leftrightarrow

Electrical

V (potential)
 I (current)
 q (charge)
 L (inductance)
 R (resistance)
 $1/C$ (capacitance)

state
variables



Sensory cells of the inner ear can behave like RLC circuits

- Voltage-gated channels (e.g., calcium-activated “BK” potassium channels) have intrinsic dynamics that can give rise to electric tuning

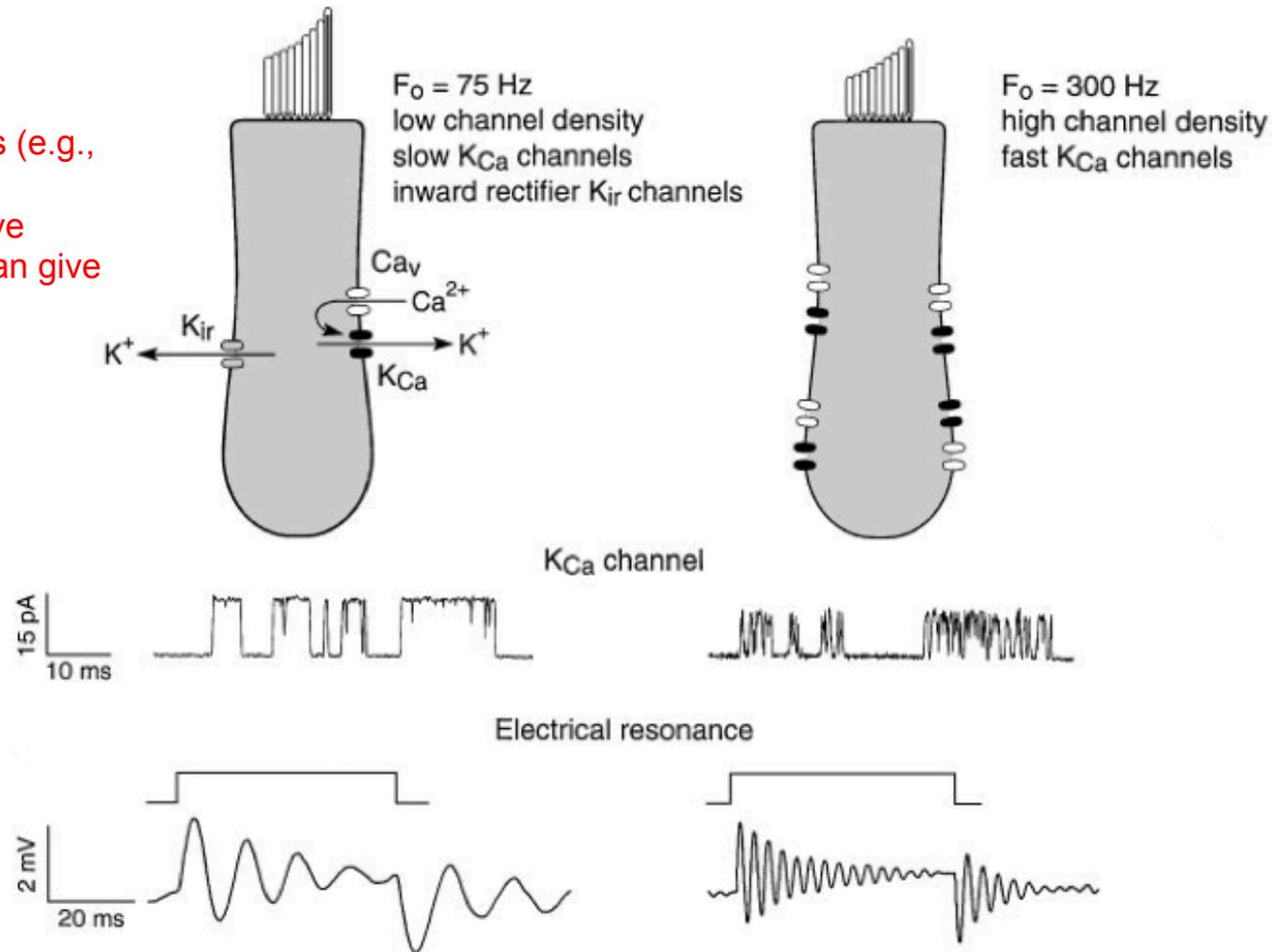


Figure 1 Schematic drawing of two hair cells from the turtle basilar papilla, with resonant frequencies (F_0) of 75 and 300 Hz. The low-frequency cell has a longer hair bundle, and a low density of Ca^{2+} and Ca^{2+} -activated K^+ (K_{Ca}) channel complexes. The number of channel complexes increases with (F_0). Beneath each cell are shown representative K_{Ca} (BK) single-channel records and ringing voltage responses to extrinsic current steps for cells tuned approximately to these two frequencies. The timing of the extrinsic current is shown above the voltage records. The single-channel records and the voltage ringing were from different sets of experiments (22, 23).

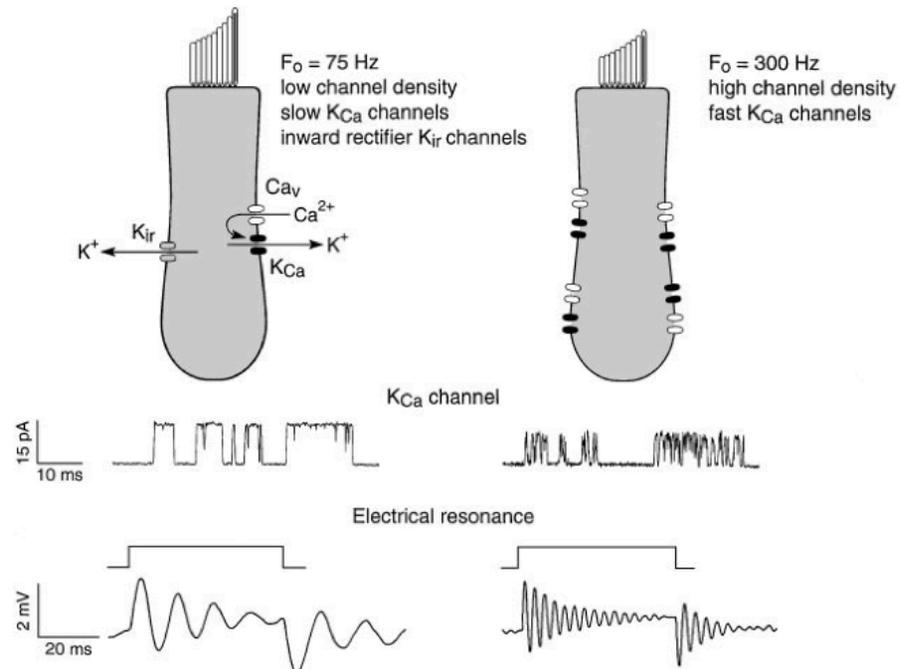
Sensory cells of the inner ear can behave like RLC circuits

1. Mechanical motion deflects bundle, causing a transduction current to depolarize the cell

2. “Depolarization opens voltage-gated Ca^{2+} channels, promoting a rise in internal Ca^{2+} that activates BK channels”

3. “The large outward K^+ current hyperpolarizes the membrane, closing the Ca^{2+} channels, which leads to the first cycle of the oscillation”

4. “As the cell hyperpolarizes and intracellular Ca^{2+} transients dissipate, the BK channels partially close, but due to the continued extrinsic current, the membrane swings positive to initiate another cycle of Ca^{2+} influx.”



“Since the BK channels are already partly activated, a smaller fraction of K^+ current is recruited on the second cycle, which will have a smaller amplitude than the first. Because the K^+ equilibrium potential (-80 mV) is negative to the resting potential (-50 mV), the BK channels behave as part of a negative feedback loop, but the time course of their activation delays the feedback and hence generates damped oscillatory responses. Such negative feedback also produces sharp tuning for sinusoidal stimuli, and the frequency at which the cell is maximally sensitive, the resonant frequency, should be influenced by the size and speed of the feedback.”

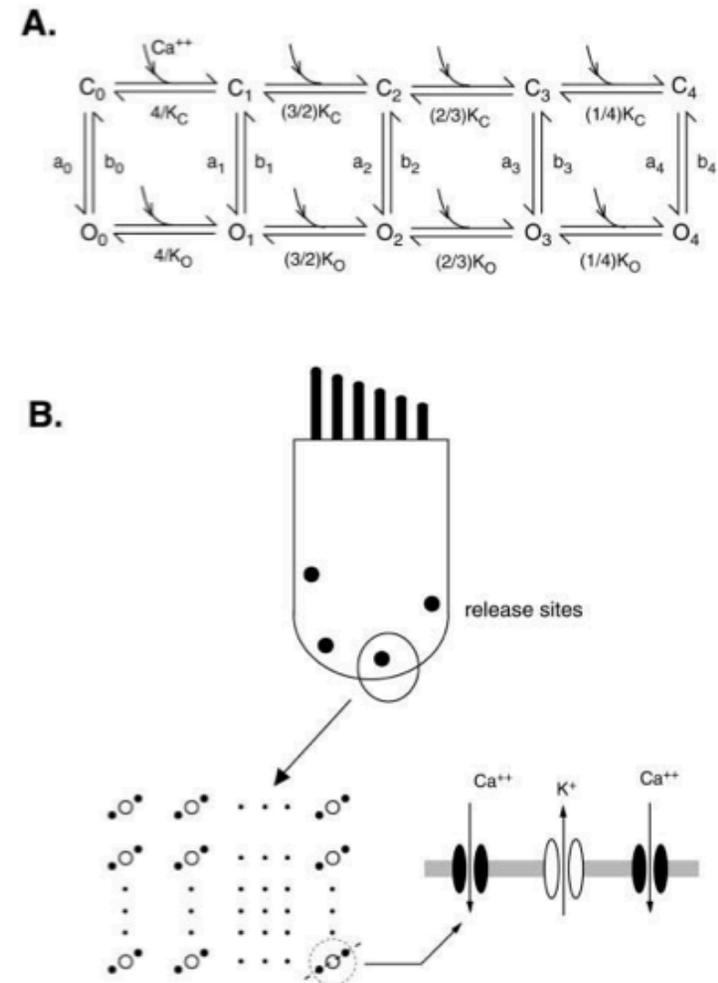
Modeling Hair Cell Tuning by Expression Gradients of Potassium Channel β Subunits

Krishnan Ramanathan and Paul A. Fuchs

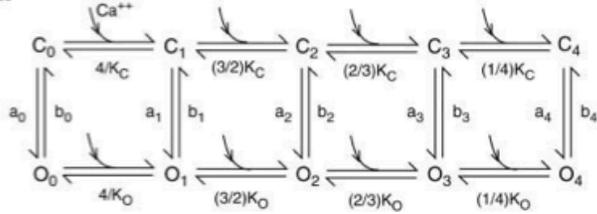
The Center for Hearing and Balance, Department of Biomedical Engineering and Department of Otolaryngology, Head and Neck Surgery, Johns Hopkins University School of Medicine, Baltimore, Maryland 21205-2195 USA

ABSTRACT The receptor potential of sensory hair cells arises from the gating of mechanosensitive cation channels, but its amplitude and time course also depend on the number and kinetics of voltage-gated ion channels in each cell. Prominent among these are “BK” potassium channels encoded by the *slo* gene that support electrical tuning in some hair cells. Hair cells tuned to low frequencies have slowly gating BK channels, whereas those of higher-frequency hair cells gate more rapidly. Alternative splicing of the *slo* gene mRNA that encodes the pore-forming α subunit can alter BK channel kinetics, and gating is dramatically slowed by coexpression with modulatory β subunits. The effect of the β subunit is consistent with low-frequency tuning, and β mRNA is expressed at highest levels in the low frequency apex of the bird’s auditory epithelium. How might an expression gradient of β subunits contribute to hair cell tuning? The present work uses a computational model of hair cell-tuning based on the functional properties of BK channels expressed from hair cell α and β *slo* cDNA. The model reveals that a limited tonotopic gradient could be achieved simply by altering the fraction of BK channels in each hair cell that are combined with β subunits. However, complete coverage of the tuning spectrum requires kinetic variants in addition to those modeled here.

FIGURE 1 BK channel and hair cell models. (A) The allosteric (voltage-dependent MWC) scheme for BK channels has horizontal transitions that are calcium dependent and vertical transitions that are voltage dependent. The voltage-dependent MWC version assumes that each calcium-binding step has the same affinity. However, binding of calcium to the closed states may differ from the binding to the open states. The subscripts to the closed and open states indicate the number of calcium ions bound. Voltage-dependent gate movements between closed and open states are thought to occur allosterically with a single rate constant. a_x and b_x are the vertical transition rates that are dependent upon voltage. K_{CX} and K_{OX} are the dissociation constants for the binding of x^{th} calcium ion to the closed and open states respectively. (B) The hair cell model incorporates BK channels into functional units with two adjacent voltage-gated calcium channels. These are shown as clusters, as might occur at transmitter release active zones, but each BK channel is gated independently by its associated calcium channels. The number and kinetic properties of BK channels varies between model cells, but the ratio of two calcium channels to one BK channel remains constant, as do the gating properties of the voltage-gated calcium channels.



A.



B.

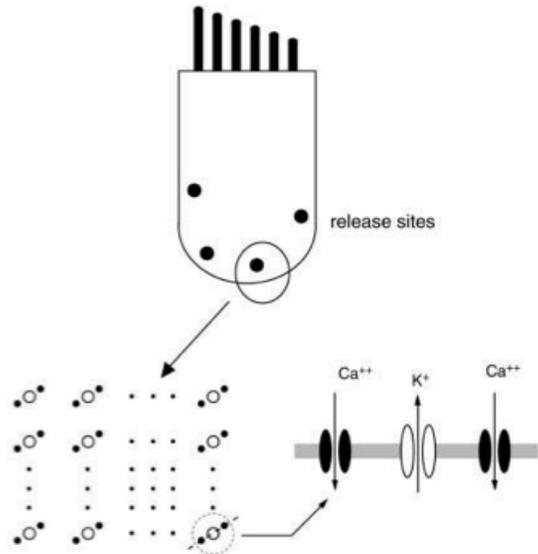


FIGURE 5 Electrical tuning of model hair cells expressing four types of BK channels. Model hair cells expressing 1 of the 4 channel types were subject to current injection of 100 pA to excite electrical resonance. Channel numbers and model parameters were varied for each trial. Channels with faster kinetics (α_0 and α_{61}) were present in larger numbers whereas those with β subunits were present in smaller numbers (Wu et al., 1995). The four channels span a electrical tuning frequency range from 88 Hz to 282 Hz. The resonant frequency and the quality of tuning for positive current injection are shown below each trace. α_0 and α_{61} produced electrical resonance at resting hair cell voltages of ~ -55 mV. Hair cells containing $\alpha_0\beta$ or $\alpha_{61}\beta$ resonated at resting potentials that were more depolarized (~ -25 mV).

