PHYS 1010 6.0: CLASS TEST 2
Time: 50 minutes; Calculators \& formulae provided at the end $=$ only aid; Total $=20$ points.
1)[5] A crate $\left(m=1.0 \times 10^{2} \mathrm{~kg}\right)$ needs to be pulled across a smooth floor by John and Bob as shown in the figure. The friction coefficients are known as $\mu_{s}=0.25, \mu_{k}=0.10$. The crate location at time $t=0$ is shown, John pulls with $F_{\mathrm{J}}=1.0 \times 10^{2} \mathrm{~N}$, and Bob with $F_{\mathrm{B}}=2.0 \times 10^{2}$ N at the angles indicated. Provide answers for $x(t)$ and $y(t)$, i.e., for the position vector of the motion. Start with a free-body diagram (include friction!). Will the crate move?

Free-body diagram
(1)
(all parts reasonable, not quantitative)
$\vec{F}_{B}+\vec{F}_{J}$ give direction of motion


$$
\vec{F}_{s}, \vec{F}_{k} \text { opposes }
$$

Determine the maximal static friction force:

$$
F_{s, \max }=\mu_{s} N=\mu_{s} m g=0.25 \times 100 \mathrm{~kg} \times 9.8 \frac{\mathrm{~m}}{\mathrm{~s}^{2}}=245 \mathrm{~N}
$$

The net pulling force: $\vec{F}_{p}=\vec{F}_{J}+\vec{F}_{B}$
Does it exceed $F_{S, \text { max }}$ ? We need: $\left|\vec{F}_{p}\right|=\sqrt{F_{P_{1 x}}}$
$F_{\text {pule, } x}=200 \cos \left(60^{\circ}\right)+100 \cos \left(30^{\circ}\right)$ in $S I(N)$

$$
=100+86.6=186.6 \mathrm{~N}
$$

$$
g_{\text {motion }}=\tan ^{-1}\left(\frac{F_{\text {pull ,y }}}{F_{\text {pull, }}}\right)=\tan ^{-1}(0.660)=33.4^{\circ}(\text { writ }+ \text { tue x-axis) })
$$

$$
\begin{aligned}
& F_{p}=\left|\vec{F}_{p}\right|=\sqrt{186.6^{2}+123.2^{2}} N=224 \mathrm{~N} \\
& \text { No motion, since static friction is not over come } \begin{array}{l}
x(t)=0 \\
y(t)=0
\end{array}
\end{aligned}
$$

2) [5] Derive the formula for the centripetal acceleration $\left(a_{\mathrm{cp}}=\frac{v^{2}}{r}\right)$ from the position vector describing uniform circular motion (formula sheet!), and show the direction for the acceleration vector.

$$
\begin{align*}
& \vec{r}(t)=R \cos \omega t \hat{\imath}+R \sin \omega t \hat{\jmath} \\
& \vec{v}(t)=\frac{d \vec{r}}{d t}=-R \omega \sin \omega t \hat{\imath}+R \omega \cos \omega t \hat{\jmath} \\
& \vec{a}(t)=\frac{d \vec{v}}{d t}=-R \omega^{2} \cos \omega t \hat{\imath}-R \omega^{2} \sin \omega t \hat{\jmath} \\
& =-\omega^{2} \vec{r}(t) 0.5
\end{align*}
$$

$\vec{a}$ opposes $\vec{r}$, points to the centre of the circle 0.5

$$
\begin{aligned}
& a_{c p}=|\vec{a}|=\sqrt{a_{x}^{2}+a_{y}^{2}}=\omega^{2}|\vec{r}|=\omega^{2} R \\
& \text { why? } \left.\quad \begin{array}{rl}
|\vec{r}(t)| & =\sqrt{x(t)^{2}+y(t)^{2}}=\sqrt{R^{2} \cos ^{2} \omega t+R^{2} \sin ^{2} \omega t} \\
= & R \sqrt{\cos ^{2} \omega t+\sin ^{2} \omega t}=R \quad \begin{array}{l}
\text { by trig } \\
\text { relation } \\
\left.\sin ^{2}+\cos ^{2}=1\right)
\end{array}
\end{array}\right\} .
\end{aligned}
$$

From $\vec{v}(t)$ show: $v(t)=|\vec{v}(t)|=\sqrt{R^{2} \omega^{2}\left(\sin ^{2} \omega t+\cos ^{2} \omega t\right)}$

$$
\begin{aligned}
&=R \omega \\
& \therefore \quad a_{c p}=\omega^{2} R=v \quad \text { (cost.) } \\
&\left(\frac{v}{R}\right)^{2} R=\frac{v^{2}}{R}
\end{aligned}
$$

$\left[\begin{array}{l}R \text { is the constant radius of the circular motion } \\ \text { and is denoted by } r=|\vec{r}(t)| \text {, ie., } a_{c_{p}}=\frac{v^{2}}{r}\end{array}\right]$ optional
3) [5] Calculate the earth's linear speed in its motion around the sun starting from the law of gravity and Newton's $2^{\text {nd }}$ law. Assume $d_{\text {STE }}=1.5 \times 10^{11} \mathrm{~m}$, and $M_{S}=2.0 \times 10^{30} \mathrm{~kg}$. Then calculate the length of a year from one orbit.

$$
\begin{align*}
& m \vec{a}=\vec{F}_{\text {net }} \longrightarrow \vec{F}_{\text {SonE }} \text { provides centripetal } a c c . \\
& M_{E} \frac{v^{2}}{d / S E}=\frac{G M_{E} M_{S}}{d_{S E}^{2}}-2 \\
& v^{2}=\frac{G M_{S}}{d_{S E}}=\frac{6.67 \times 10^{-11} \cdot 2.0 \times 10^{30}}{1.5 \times 10^{11}}=8.9 \times 10^{8} \frac{\mathrm{~m}^{2}}{\mathrm{~s}^{2}} \\
& v=3.0 \times 10^{4} \frac{\mathrm{~m}}{\mathrm{~s}}=30 \frac{\mathrm{~km}}{\mathrm{~s}}
\end{align*}
$$

Orbit length: $\quad S=2 \pi d_{S E} ; \quad S=v T$

$$
\begin{align*}
\therefore \quad T=\frac{s}{v}=\frac{2 \pi d_{S E}}{v} & =0.314 \times 10^{8} \mathrm{~S}  \tag{1}\\
& =3.1 \times 10^{7} \mathrm{~s} \tag{1}
\end{align*}
$$

[makes sense?

$$
\begin{gathered}
365 \times 24 \times 3600=31,536,000 \sim 3.2 \times 10^{7}- \\
\text { optional }
\end{gathered}
$$

4) [5] When you compress a spring the force increases linearly with the displacement from equilibrium $\Delta x$. Calculate the work associated with this compression. Do the calculation based on geometry, do not use integral calculus, i.e., start with a graph of the spring force vs displacement $\Delta x$. By Hooke's law $F=-k \Delta x$, and note that $\Delta x$ can be positive or negative.


Area of the triangle:
$\frac{1}{2}$ (base $x$ height) $\quad \begin{aligned} & A=\frac{1}{2} \Delta x \cdot(-k \Delta x) \\ & =-\frac{1}{2} k \Delta x^{2}\end{aligned}$

$$
\frac{1}{2} \text { (base } x \text { height) }
$$

The work done by the spring force: $-\frac{1}{2} k \Delta x^{2}$
["-"sign: we have to work against the spring] opt
FORMULA SHEET
$v\left(t_{\mathrm{f}}\right)=v\left(t_{\mathrm{i}}\right)+\int_{t_{\mathrm{i}}}^{t_{\mathrm{f}}} a(t) d t \quad s\left(t_{\mathrm{f}}\right)=s\left(t_{\mathrm{i}}\right)+\int_{t_{\mathrm{i}}}^{t_{\mathrm{f}}} v(t) d t$
$v_{\mathrm{f}}=v_{\mathrm{i}}+a \Delta t \quad s_{\mathrm{f}}=s_{\mathrm{i}}+v_{\mathrm{i}} \Delta t+\frac{1}{2} a \Delta t^{2} \quad v_{\mathrm{f}}^{2}=v_{\mathrm{i}}^{2}+2 a \Delta s \quad g=9.8 \mathrm{~m} / \mathrm{s}^{2}$
$f(t)=t \quad \frac{d f}{d t}=1 \quad F(t)=\int f(t) d t=\frac{t^{2}}{2}+C$
$f(t)=a \quad \frac{d f}{d t}=0 \quad F(t)=\int f(t) d t=a t+C \quad F(t)=$ anti-derivative $=$ indefinite integral
area under the curve $f(t)$ between limits $t_{1}$ and $t_{2}: F\left(t_{2}\right)-F\left(t_{1}\right)$
$x^{2}+p x+q=0$ factored by: $x_{1,2}=-\frac{p}{2} \pm \sqrt{\frac{p^{2}}{4}-q}$
uniform circular m. $\vec{r}(t)=R(\cos \omega t \hat{\mathbf{i}}+\sin \omega t \hat{\mathbf{j}}) ; \vec{v}(t)=\frac{d \vec{r}}{d t}=\ldots ; \quad \vec{a}(t)=\frac{d \vec{v}}{d t}=\ldots$.
$\exp ^{\prime}=\exp ; \quad \sin ^{\prime}=\cos ; \quad \cos ^{\prime}=-\sin . \quad \frac{d}{d x}[f(g(x))]=\frac{d f}{d g} \frac{d g}{d x} ; \quad(f g)^{\prime}=f^{\prime} g+f g^{\prime}$
$m \vec{a}=\vec{F}_{\text {net }} ; \quad F_{G}=\frac{G m_{1} m_{2}}{r^{2}} ; g=\frac{G M_{E}}{R_{E}^{2}} ; R_{E}=6370 \mathrm{~km} ; G=6.67 \times 10^{-11} \frac{\mathrm{Nm}^{2}}{\mathrm{~kg}^{2}} ; M_{E}=6.0 \times 10^{24} \mathrm{~kg}$
$f_{\mathrm{s}} \leq \mu_{\mathrm{s}} n ; \quad f_{\mathrm{k}}=\mu_{\mathrm{k}} n ; \quad f_{\mathrm{r}}=\mu_{\mathrm{r}} n ; \quad \mu_{\mathrm{r}} \ll \mu_{\mathrm{k}}<\mu_{\mathrm{s}} . \quad F_{H}=-k \Delta x=-k\left(x-x_{0}\right)$.
$\vec{F}_{\mathrm{d}} \sim-\vec{v}$; linear: $F_{\mathrm{d}}=d v$; quadratic: $F_{\mathrm{d}}=0.5 \rho A v^{2} ; \quad A=$ cross sectional area
$W=F \Delta x=F(\Delta r) \cos \theta \quad$ For $F(x)$ the work is given as area under the $F_{x}$ vs $x$ curve.

