

LAST NAME:

STUDENT NR:

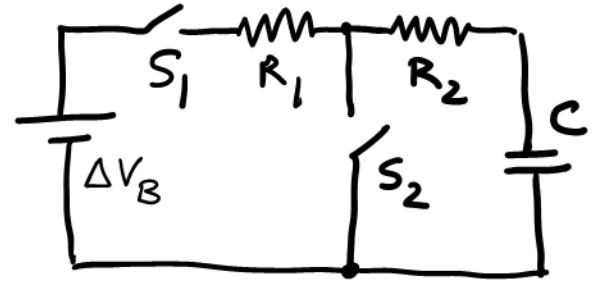
PHYS 1010 6.0: CLASS TEST 5

Time: 50 minutes; Calculators & formulae provided at the end = only aid; Total = 20 points.

1) [5] The capacitor in the circuit shown is initially uncharged. a) What is the battery current right after switch S_1 is closed? b) S_1 was closed now for a long time. At time t_1 simultaneously S_1 is opened and S_2 is closed. What is the current through S_2 at this instant. c) A long time later $t_2 \gg t_1$ (while S_2 is closed) what is the the current through S_2 ?

$$C = 90 \mu\text{F}, \quad R_1 = 2.2 \text{ k}\Omega,$$

$$\Delta V_B = 3.0 \text{ V}, \quad R_2 = 4.9 \text{ k}\Omega$$



a) $R_{eq} = R_1 + R_2 = 7.1 \text{ k}\Omega$, ①

C has $Q=0$, i.e., $\Delta V_C = \frac{Q}{C} = 0 \therefore I(0) = \frac{\Delta V_B}{R_{eq}}$

$$I(0) = \frac{3.0}{7.1 \times 10^3} = 0.42 \text{ mA}$$
 ①.5

← includes reasoning (intermediate steps)

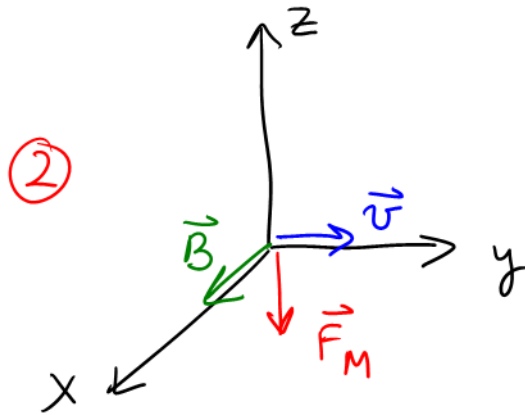
b) discharge current, $\Delta V_C = \Delta V_B$, since $I(\infty) = 0$
no voltage drop across R_1 or R_2

$$I(t_1) = \frac{\Delta V_C}{R_2} = \frac{3.0 \text{ V}}{4.9 \text{ k}\Omega} = 0.61 \text{ mA}$$
 ①.5

direction is ↻

c) $I(\infty) = 0$, since $I(t) = I_0 e^{-t/\tau}$, where
① $\tau = R_2 C$

2) [5] An alpha particle is a helium nucleus (two protons and two neutrons bound together). If it moves along the positive y -axis and experiences a magnetic force along the negative z -axis, what can you conclude about the direction of \vec{B} ? Begin with a sketch indicating all vectors involved, and explain your reasoning.



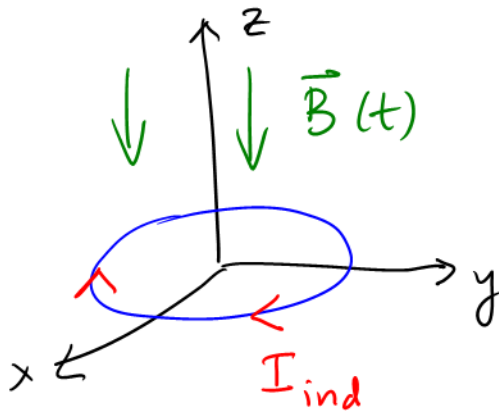
$$F = q \vec{v} \times \vec{B} \quad \textcircled{1}$$

$$q = 2e > 0$$

The magnetic field is along the positive x -axis
 $\vec{B} = (B, 0, 0) = B \hat{x} \quad \textcircled{2}$

By the RH rule

3) [5] A circular loop of wire lies in the $x - y$ plane. A time-varying magnetic field is given as $\vec{B} = (0, 0, -B(t))$, with the field strength $B(t)$ decreasing over time. a) Explain the direction of the induced current. (b) The wire loop has a resistance of $R = 1\Omega$, and a diameter of 1 cm. The constant rate at which the field decreases is -0.1 T/s . Calculate the current in the loop and the power dissipated.



a) The strength of \vec{B} is decreasing. By the Lenz rule \vec{B}_{ind} will support \vec{B} , i.e.,

$$\vec{B}_{\text{ind}} = (0, 0, -B_{\text{ind}})$$

$$= -B_{\text{ind}} \hat{k} \quad (1)$$

By the simple RH rule the induced current is CW when viewed from above (1)

b) $d = 1 \text{ cm} = 10^{-2} \text{ m}$ \therefore loop area = $A = \pi \frac{d^2}{4}$
 $A = 7.85 \times 10^{-5} \text{ m}^2$ (0.5)

$\Phi_M = B(t) A$ since $\vec{B} \perp$ to loop area

$\frac{d\Phi_M}{dt} = \frac{dB}{dt} A$ $\frac{dB}{dt} = -0.1 \frac{\text{T}}{\text{s}}$
 (0.5)

$\mathcal{E} = - \frac{d\Phi_M}{dt} = -A \frac{dB}{dt} = 7.85 \times 10^{-5} \times 10^{-1} \frac{\text{Tm}^2}{\text{s}}$
 $= 7.85 \mu\text{V}$
 (0.5)

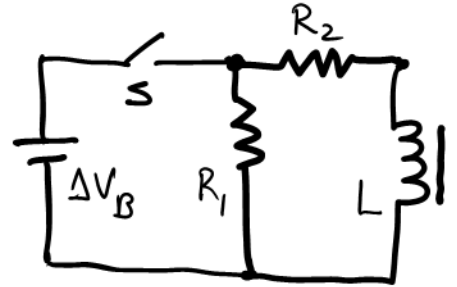
$I = \frac{\mathcal{E}}{R} = \frac{7.85 \times 10^{-6} \text{ V}}{1 \Omega} = 7.85 \mu\text{A}$ (2) includes partial steps

$P = \mathcal{E} I = 7.85^2 \times 10^{-12} \text{ W} = 6.2 \times 10^{-11} \text{ W}$ (1)
 (0.5)

4) [5] In the diagram shown switch S was open a long time, and it is closed at $t = 0$. a) What is the current I_1 and I_2 through R_1 and R_2 respectively at $t = 0$, just when S is closed? b) What is the voltage across inductor L at $t = 0$ (S closed), i.e., $\Delta V_L(0)$? c) S was closed now for a long time. What are the currents I_1 , I_2 (through R_1 , R_2 respectively), and the inductor voltage ΔV_L ? d) A long time later S is re-opened at t_0 . What is the magnitude and direction of $I_1(t_0)$ (after re-opening)? e) What is the inductor voltage $\Delta V_L(t_0)$ at this time?

$$\Delta V_B = 9.0 \text{ V}, \quad R_1 = 0.5 \text{ k}\Omega,$$

$$R_2 = 1.2 \text{ k}\Omega, \quad L = 3.0 \text{ mH}$$



a) $I_1 = \frac{\Delta V_B}{R_1} = 18 \text{ mA}$ (0.5)

$I_2 = 0$ (0.5)

b) $\Delta V_L(0) = -\Delta V_B$ (0.5)

c) $I_1 = 18 \text{ mA}$ (0.5), $I_2 = \frac{\Delta V_B}{R_2} = 7.5 \text{ mA}$ (0.5)

d) I_2 continues, $|I_1(t_0)| = I_2 = 7.5 \text{ mA}$ ↑ (0.5)

The direction is opposite to the original I_1 (0.5)

e) To pass $I_2 = 7.5 \text{ mA}$ through the circuit with $R_{eq} = R_1 + R_2 = 1.7 \text{ k}\Omega$ we need

$$\mathcal{E} = R_{eq} I_2 = 1.7 \times 10^3 \cdot 7.5 \times 10^{-3} \text{ V}$$

$$= 12.75 \text{ V} = 13 \text{ V}$$
 (1.5)

FORMULA SHEET

$$v(t_f) = v(t_i) + \int_{t_i}^{t_f} a(t) dt \quad s(t_f) = s(t_i) + \int_{t_i}^{t_f} v(t) dt$$

$$v_f = v_i + a\Delta t \quad s_f = s_i + v_i\Delta t + \frac{1}{2}a\Delta t^2 \quad v_f^2 = v_i^2 + 2a\Delta s \quad g = 9.8 \text{ m/s}^2$$

$$f(t) = t \quad \frac{df}{dt} = 1 \quad F(t) = \int f(t) dt = \frac{t^2}{2} + C$$

$$f(t) = a \quad \frac{df}{dt} = 0 \quad F(t) = \int f(t) dt = at + C \quad F(t) = \text{anti-derivative} = \text{indefinite integral}$$

area under the curve $f(t)$ between limits t_1 and t_2 : $F(t_2) - F(t_1)$

$$x^2 + px + q = 0 \text{ factored by: } x_{1,2} = -\frac{p}{2} \pm \sqrt{\frac{p^2}{4} - q}$$

$$\text{uniform circular m. } \vec{r}(t) = R(\cos \omega t \hat{i} + \sin \omega t \hat{j}); \quad \vec{v}(t) = \frac{d\vec{r}}{dt} = \dots; \quad \vec{a}(t) = \frac{d\vec{v}}{dt} = \dots$$

$$\exp' = \exp; \quad \sin' = \cos; \quad \cos' = -\sin. \quad \frac{d}{dx}[f(g(x))] = \frac{df}{dg} \frac{dg}{dx}; \quad (fg)' = f'g + fg'$$

$$m\vec{a} = \vec{F}_{\text{net}}; \quad F_G = \frac{Gm_1m_2}{r^2}; \quad g = \frac{GM_E}{R_E^2}; \quad R_E = 6370 \text{ km}; \quad G = 6.67 \times 10^{-11} \frac{\text{Nm}^2}{\text{kg}^2}; \quad M_E = 6.0 \times 10^{24} \text{ kg}$$

$$f_s \leq \mu_s n; \quad f_k = \mu_k n; \quad f_r = \mu_r n; \quad \mu_r \ll \mu_k < \mu_s. \quad F_H = -k\Delta x = -k(x - x_0).$$

$$\vec{F}_d \sim -\vec{v}; \text{ linear: } F_d = dv; \text{ quadratic: } F_d = 0.5\rho A v^2; \quad A = \text{cross sectional area}$$

$$W = F\Delta x = F(\Delta r) \cos \theta. \quad W = \text{area under } F_x(x). \quad PE_H = \frac{k}{2}(\Delta x)^2; \quad PE_g = mg\Delta y.$$

$$\Delta \vec{p} = \vec{J} = \int \vec{F}(t) dt; \quad \Delta p_x = J_x = \text{area under } F_x(t) = F_x^{\text{avg}} \Delta t; \quad \vec{p} = m\vec{v}; \quad K = \frac{m}{2}v^2$$

$$\Delta \vec{p}_1 + \Delta \vec{p}_2 = 0; \quad K_1^{\text{in}} + K_2^{\text{in}} = K_1^{\text{fin}} + K_2^{\text{fin}} \text{ for elastic collisions.} \quad \vec{a}_{\text{CM}} = \frac{m_1\vec{a}_1 + m_2\vec{a}_2}{m_1 + m_2}$$

$$\vec{\tau} = \vec{r} \times \vec{F}; \quad \tau_z = rF \sin(\alpha) \text{ for } \vec{r}, \vec{F} \text{ in } xy \text{ plane.} \quad I = \sum_i m_i r_i^2; \quad I\alpha_z = \tau_z; \quad (\hat{k} = \text{rot. axis})$$

$$K_{\text{rot}} = \frac{I}{2}\omega^2; \quad L_z = I\omega_z; \quad \frac{d}{dt}L_z = \tau_z; \quad \vec{L} = \vec{r} \times \vec{p}; \quad \frac{d}{dt}\vec{L} = \vec{\tau}$$

$$x(t) = A \cos(\omega t + \phi); \quad \omega = \frac{2\pi}{T} = 2\pi f; \quad v_x(t) = \dots; \quad v_{\text{max}} = \dots$$

$$m_e = 9.11 \times 10^{-31} \text{ kg} \quad m_p = 1.67 \times 10^{-27} \text{ kg} \quad e = 1.60 \times 10^{-19} \text{ C} \quad k = \frac{1}{4\pi\epsilon_0} = 9.0 \times 10^9 \frac{\text{Nm}^2}{\text{C}^2}$$

$$\vec{F}_C = \frac{kq_1q_2}{r^2} \hat{r} \quad \vec{F}_E = q\vec{E} \quad E_{\text{line}} = \frac{2k|\lambda|}{r} = \frac{2k|Q|}{Lr} \quad E_{\text{plane}} = \frac{|\eta|}{2\epsilon_0} = \frac{|Q|}{2A\epsilon_0} \quad \vec{E}_{\text{cap}} = \left(\frac{Q}{\epsilon_0 A}, \text{pos} \rightarrow \text{neg}\right)$$

$$\frac{mv^2}{2} + U_{\text{el}}(s) = \frac{mv_0^2}{2} + U_{\text{el}}(s_0), \quad (U \equiv PE_{\text{el}}) \quad U_{\text{el}} = qEx \text{ for } \vec{E} = -E\hat{i} \quad V_{\text{el}} = U_{\text{el}}/q \quad E_x = -\frac{dV_{\text{el}}}{dx}$$

$$Q = C\Delta V_C \quad \text{farad} = F = \frac{C}{V} \quad C = \frac{\epsilon_0 A}{d} \quad \epsilon_0 = 8.85 \times 10^{-12} \frac{\text{C}^2}{\text{Nm}^2}$$

$$\text{parallel } C_1, C_2: C_{\text{eq}} = C_1 + C_2 \quad \text{series } C_1, C_2: C_{\text{eq}}^{-1} = C_1^{-1} + C_2^{-1}$$

$$\Delta V_{\text{loop}} = \sum_i \Delta V_i = 0 \quad \sum I_{\text{in}} = \sum I_{\text{out}}$$

$$P = \Delta VI \quad \text{watt} = W = VA \quad P_R = \Delta V_R I = I^2 R$$

$$\tau = RC \quad Q(t) = Q_0 e^{-t/\tau} \quad I(t) = -\frac{dQ}{dt} = \frac{\Delta V_0}{R} e^{-t/\tau}$$

$$\vec{B} = \frac{\mu_0}{4\pi} \frac{q\vec{v} \times \vec{r}}{r^3} = \frac{\mu_0}{4\pi} \frac{I\Delta\vec{s} \times \vec{r}}{r^3} \quad B_{\text{wire}} = \frac{\mu_0 I}{2\pi d} \text{ (use RH rule)} \quad \frac{\mu_0}{4\pi} = 10^{-7} \frac{\text{Tm}}{\text{A}} \quad \text{tesla} = \text{T} = \frac{\text{N}}{\text{Am}}$$

$$\text{short coil, } R \gg L \text{ (} N \text{ turns): } B_{\text{coil,centre}} = \frac{\mu_0 NI}{2R} \quad \text{solenoid, } L \gg R: B_{\text{sol,inside}} = \frac{\mu_0 NI}{L}$$

$$\text{mag dipole: } \vec{\mu} = (AI, \text{ from south to north}) \quad \vec{B}_{\text{dip}} = \frac{\mu_0}{4\pi} \frac{2\vec{\mu}}{z^3} \text{ on axis, far away}$$

$$\vec{F}_{\text{onq}} = q\vec{v} \times \vec{B} \quad \text{force on current } \perp \text{ to } \vec{B}: F_{\text{wire}} = ILB$$

$$\text{force betw. parallel wires: } F_{2\text{wires}} = \frac{\mu_0 I_1 I_2}{2\pi d} \quad \text{torque on mag dipole: } \vec{\mu} \text{ in } \vec{B}: \vec{\tau} = \vec{\mu} \times \vec{B}$$

$$\text{bar (length } L) \text{ moves w. } \vec{v} \perp \vec{B} \text{ gen. EMF: } \varepsilon = vLB;$$

$$\Phi_m = \vec{A} \cdot \vec{B} \quad \Phi_m = AB \cos \theta \quad \varepsilon = \left| \frac{d\Phi_m}{dt} \right| = \left| \vec{B} \cdot \frac{d\vec{A}}{dt} + \vec{A} \cdot \frac{d\vec{B}}{dt} \right|$$

$$L = \frac{\Phi_m}{I} \quad \text{henry} = \text{H} = \frac{\text{Tm}^2}{\text{A}} \quad \varepsilon_{\text{coil}} = L \left| \frac{dI}{dt} \right| \quad \Delta V_L = -L \frac{dI}{dt} \quad PE_L = \frac{L}{2} I^2$$

$$\text{series L and R: } \tau = \frac{L}{R} \quad I(t) = I_0(1 - e^{-t/\tau})$$