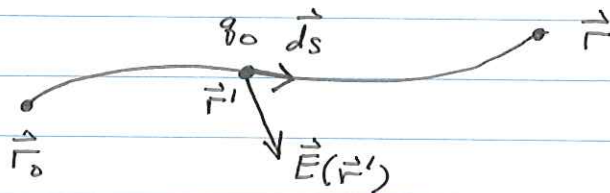


II. Electric potential

Consider a test charge q_0 in an electric field \vec{E} .
The force acting on q_0 is $\vec{F} = q_0 \vec{E}$.

What is the work required to move q_0 from an initial position \vec{r}_0 to an arbitrary final position \vec{r} ?

$$W = - \int_{\vec{r}_0}^{\vec{r}} \vec{ds} \cdot \vec{F}(\vec{r}') = -q_0 \int_{\vec{r}_0}^{\vec{r}} \vec{ds} \cdot \vec{E}(\vec{r}')$$



Let $\vec{r}' = (x', y', z')$ be position along path from \vec{r}_0 to \vec{r} .
 $\vec{ds} = (dx', dy', dz')$ points along path.

The electric potential is defined as $\phi(\vec{r}) = - \int_{\vec{r}_0}^{\vec{r}} \vec{ds} \cdot \vec{E}(\vec{r}')$

$$W = q_0 \phi(\vec{r})$$

$$\phi(\vec{r}) = \frac{W}{q_0} = \text{Work-per-charge to move a test charge from } \vec{r}_0 \text{ to } \vec{r}.$$

Since \vec{F} is conservative for electrostatic forces,
 $\phi(\vec{r})$ does not depend on path.

Note: $\phi(\vec{r})$ is defined with respect to a reference point \vec{r}_0 where $\phi(\vec{r}_0) = 0$.

Defining a "new" potential with respect to a different reference point \vec{r}_1 is same as adding a constant.

$$\begin{aligned} \phi_{\text{new}}(\vec{r}) &= - \int_{\vec{r}_1}^{\vec{r}} \vec{ds} \cdot \vec{E} = - \int_{\vec{r}_0}^{\vec{r}} \vec{ds} \cdot \vec{E} - \underbrace{\int_{\vec{r}_0}^{\vec{r}_1} \vec{ds} \cdot \vec{E}}_{\text{const. in } \vec{r}} \\ &= \phi_{\text{old}}(\vec{r}) + \text{constant} \end{aligned}$$

Usual convention: $\vec{r}_0 \rightarrow \infty$. $\phi = 0$ for $r \rightarrow \infty$.

$$\phi(\vec{r}) = - \int_{\infty}^{\vec{r}} \vec{ds} \cdot \vec{E}(\vec{r}')$$

$\Delta U(\vec{r}) = q_0 \phi(\vec{r}) =$ change in potential energy by bringing in test charge q_0 from ∞ to position $\bullet \vec{r}$.

The potential difference ϕ_{21} between two points \vec{r}_1 and \vec{r}_2 is:

$$\begin{aligned} \phi_{21} &= \phi(\vec{r}_2) - \phi(\vec{r}_1) = - \int_{\vec{r}_0}^{\vec{r}_2} \vec{ds} \cdot \vec{E} + \int_{\vec{r}_0}^{\vec{r}_1} \vec{ds} \cdot \vec{E} \\ &= - \int_{\vec{r}_0}^{\vec{r}_2} \vec{ds} \cdot \vec{E} - \int_{\vec{r}_1}^{\vec{r}_0} \vec{ds} \cdot \vec{E} = - \int_{\vec{r}_1}^{\vec{r}_2} \vec{ds} \cdot \vec{E} \end{aligned}$$

$$W_{21} = q_0 \phi_{21} = -q_0 \int_{\vec{r}_1}^{\vec{r}_2} \vec{ds} \cdot \vec{E} = \text{work to move } q_0 \text{ from } \vec{r}_1 \text{ to } \vec{r}_2.$$

Note: any potential difference is independent of reference point \vec{r}_0 .

example: point charge q . What is $\phi(\vec{r})$?

Recall potential energy formula for two point charges

$$U_{12} = \frac{1}{4\pi\epsilon_0} \frac{q_1 q_2}{r_{12}}$$

Here consider q with test charge q_0 , separated by distance r .

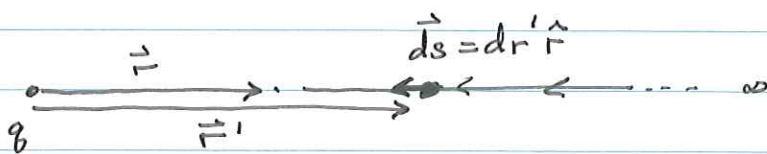
So $q_1 \rightarrow q$, $q_2 \rightarrow q_0$, $r_{12} \rightarrow r$.

$$U_{12} = \frac{1}{4\pi\epsilon_0} \frac{q q_0}{r} = \text{work to bring in } q_0 \text{ from } \infty$$

$$\text{So } \phi(r) = \frac{U_{12}}{q_0} = \frac{q}{4\pi\epsilon_0 r} \quad \left. \vphantom{\frac{q}{4\pi\epsilon_0 r}} \right\} \begin{array}{l} \text{doesn't depend} \\ \text{on } q_0 \text{ (test charge)} \end{array}$$

Or, can compute $\phi(r)$ from $\vec{E}(\vec{r}) = \frac{1}{4\pi\epsilon_0} \frac{q}{r^2} \hat{r}$

$$\phi(r) = - \int_{\infty}^r \vec{ds} \cdot \vec{E}(\vec{r}') \quad \vec{ds} = dr' \hat{r}$$



$$= - \frac{q}{4\pi\epsilon_0} \int_{\infty}^r dr' \frac{1}{r'^2} = \frac{q}{4\pi\epsilon_0 r}$$

Potential of a point charge

$$\boxed{\phi(r) = \frac{q}{4\pi\epsilon_0 r}}$$

Electric potential vs. potential energy

Consider an arbitrary charge configuration, say N point charges q_1, q_2, \dots, q_N , with electric field \vec{E} .

The potential energy U_N of the N charges is the total work required to assemble them from ∞ .

$$U_N = \sum_{i=1}^N \sum_{j=i+1}^N U_{ij} = \sum_{i=1}^N \sum_{j=i+1}^N \frac{q_i q_j}{4\pi\epsilon_0 r_{ij}}$$

The potential ϕ is related to the extra work it would require to bring in an extra charge q_0 .

$$\Delta U = q_0 \phi = \sum_{i=1}^N \frac{q_0 q_i}{4\pi\epsilon_0 r_{0i}}$$

The total potential energy of the $N+1$ charges ($q_1, \dots, q_N + q_0$) would be $U_{N+1} = U_N + \Delta U$.

example: charged spherical shell with surface charge σ and radius R .

Total charge is $Q = \sigma 4\pi R^2$

Inside sphere: $\vec{E} = 0$ by Gauss's law ($r < R$)

Outside sphere: $\vec{E} = \frac{1}{4\pi\epsilon_0} \frac{Q}{r^2} \hat{r}$ ($r > R$) same as an equivalent point charge.

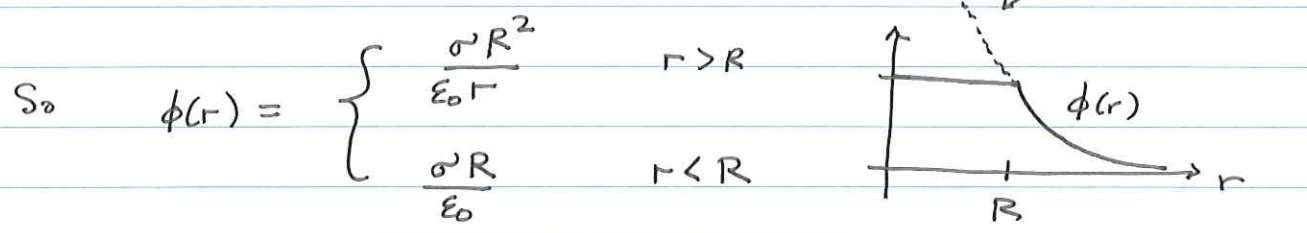
For $r > R$: $\phi(r) = \frac{Q}{4\pi\epsilon_0 r}$ (same as point charge)

Note: ϕ has SI units $\frac{\text{energy}}{\text{charge}} = \frac{\text{Joule}}{\text{Coulomb}} = \underline{\text{volts}}$

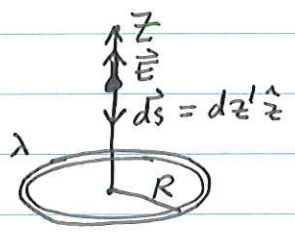
For $r < R$:
$$\phi(r) = - \int_{\infty}^r \vec{ds} \cdot \vec{E}(r') = - \int_{\infty}^r dr' E(r')$$

$$= - \int_{\infty}^R dr' E(r') - \int_{R}^r dr' E(r')$$

$$= - \int_{\infty}^R dr' \frac{Q}{4\pi\epsilon_0 r'^2} = \frac{Q}{4\pi\epsilon_0 R}$$



example: charged ring with linear charge density λ and radius R . What is $\phi(z)$ along z axis?

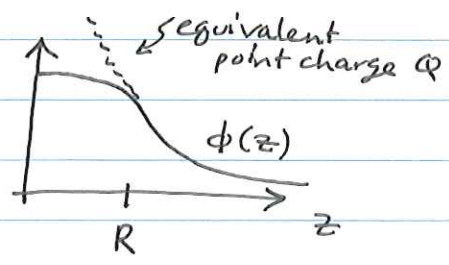


HW #2:
$$\vec{E}(z) = \frac{\lambda R z}{2\epsilon_0 (R^2 + z^2)^{3/2}} \hat{z}$$

$$\phi(z) = - \int_{\infty}^z \vec{ds} \cdot \vec{E}(z') = - \int_{\infty}^z dz' \frac{\lambda R z'}{2\epsilon_0 (R^2 + z'^2)^{3/2}} = \frac{\lambda R}{2\epsilon_0 \sqrt{R^2 + z^2}}$$

Note the total charge is $Q = \lambda \cdot 2\pi R \Rightarrow \lambda = \frac{Q}{2\pi R}$.

$$\phi(z) = \frac{Q}{4\pi\epsilon_0 \sqrt{R^2 + z^2}}$$



Everything with nonzero net charge Q looks like a point charge sufficiently far away.

Gradient & partial derivatives

We can compute ϕ from \vec{E} using line integral

$$\phi = - \int \vec{ds} \cdot \vec{E}$$

We can also compute \vec{E} from ϕ using gradient.

Partial derivatives: consider a multivariable function $f(x, y, z)$. The partial derivative $\frac{\partial f}{\partial x}$ is the derivative of f with respect to x , while treating ~~keeping~~ the other variables ~~fixed~~ as constants

e.g. $f(x, y, z) = x^2 y + x$

$$\frac{\partial f}{\partial x} = 2xy + 1$$

$$\frac{\partial f}{\partial y} = x^2$$

$$\frac{\partial f}{\partial z} = 0$$

e.g. $f(x, y, z) = \frac{1}{r} = \frac{1}{\sqrt{x^2 + y^2 + z^2}}$

$$\frac{\partial f}{\partial x} = -\frac{1}{2} \frac{1}{\sqrt{x^2 + y^2 + z^2}^{3/2}} 2x = -\frac{x}{r^3}$$

$$\frac{\partial f}{\partial y} = -\frac{y}{r^3}$$

$$\frac{\partial f}{\partial z} = -\frac{z}{r^3}$$

Taylor expansion:

Recall a function $f(x)$ can be Taylor expanded around $x=0$:

$$f(x) = f(0) + f'(0)x + \frac{1}{2!} f''(0)x^2 + \dots$$

where $f'(0) = \left. \frac{df}{dx} \right|_{x=0}$, etc.

or around $x=x_0$ as:

$$f(x) = f(x_0) + f'(x_0)(x-x_0) + \frac{1}{2!} f''(x_0)(x-x_0)^2 + \dots$$

~~where~~

Using Taylor expansion, $f(x+\Delta x)$ can be related to $f(x)$:

$$f(x+\Delta x) = f(x) + f'(x)\Delta x + \frac{1}{2!} f''(x)\Delta x^2 + \dots$$

For Δx small, $f(x+\Delta x) = f(x) + f'(x)\Delta x + \dots$

For multivariable functions, we need to use partial derivatives for Taylor expansion.

$$f(x+\Delta x, y, z) = f(x, y, z) + \frac{\partial f}{\partial x} \Delta x + \dots$$

$$f(x, y+\Delta y, z) = f(x, y, z) + \frac{\partial f}{\partial y} \Delta y + \dots$$

$$f(x, y, z+\Delta z) = f(x, y, z) + \frac{\partial f}{\partial z} \Delta z + \dots$$

More general case:

$$f(x+\Delta x, y+\Delta y, z+\Delta z) = f(x, y, z) + \frac{\partial f}{\partial x} \Delta x + \frac{\partial f}{\partial y} \Delta y + \frac{\partial f}{\partial z} \Delta z + \dots$$

Let's define $\vec{r} = (x, y, z)$, $\Delta \vec{r} = (\Delta x, \Delta y, \Delta z)$.

Introduce new operator "del" $\vec{\nabla} = \left(\frac{\partial}{\partial x}, \frac{\partial}{\partial y}, \frac{\partial}{\partial z} \right)$

$$\vec{\nabla} = \frac{\partial}{\partial x} \hat{x} + \frac{\partial}{\partial y} \hat{y} + \frac{\partial}{\partial z} \hat{z}$$

The gradient of f is defined as

$$\vec{\nabla} f = \left(\frac{\partial f}{\partial x}, \frac{\partial f}{\partial y}, \frac{\partial f}{\partial z} \right)$$

f is a scalar function (a number, no direction)
But $\vec{\nabla} f$ is a vector function.

Note: $\vec{\nabla} f \cdot \Delta \vec{r} = \frac{\partial f}{\partial x} \Delta x + \frac{\partial f}{\partial y} \Delta y + \frac{\partial f}{\partial z} \Delta z$

So we can write:

$$\underbrace{f(\vec{r} + \Delta \vec{r})}_{f(x+\Delta x, y+\Delta y, z+\Delta z)} = \underbrace{f(\vec{r})}_{f(x, y, z)} + \vec{\nabla} f \cdot \Delta \vec{r} + \dots$$

We can use gradient to compute \vec{E} from ϕ :

Consider the potential difference ~~between~~ $\Delta\phi$ between ϕ at \vec{r} and $\vec{r} + \Delta\vec{r}$.

$$\begin{aligned}\Delta\phi &= \phi(\vec{r} + \Delta\vec{r}) - \phi(\vec{r}) \\ &= - \int_{\vec{r}_0}^{\vec{r} + \Delta\vec{r}} d\vec{s} \cdot \vec{E}(\vec{r}') + \int_{\vec{r}_0}^{\vec{r}} d\vec{s} \cdot \vec{E}(\vec{r}') = - \int_{\vec{r}}^{\vec{r} + \Delta\vec{r}} d\vec{s} \cdot \vec{E}(\vec{r}')\end{aligned}$$

Assume $\Delta\vec{r}$ is small.

$$\begin{aligned}\text{Then } \Delta\phi &= \phi(\vec{r} + \Delta\vec{r}) - \phi(\vec{r}) = \phi(\vec{r}) + \vec{\nabla}\phi \cdot \Delta\vec{r} - \phi(\vec{r}) \\ &= \vec{\nabla}\phi \cdot \Delta\vec{r}\end{aligned}$$

Also, can assume \vec{E} is approx. const along path from \vec{r} to $\vec{r} + \Delta\vec{r}$.

$$\int_{\vec{r}}^{\vec{r} + \Delta\vec{r}} d\vec{s} \cdot \vec{E}(\vec{r}') = \vec{E}(\vec{r}) \cdot \left(\int_{\vec{r}}^{\vec{r} + \Delta\vec{r}} d\vec{s} \right) = \vec{E}(\vec{r}) \cdot \Delta\vec{r}$$

$$\text{Note: } \int_{\vec{r}}^{\vec{r} + \Delta\vec{r}} d\vec{s} = \int_{(x, y, z)}^{(x + \Delta x, y + \Delta y, z + \Delta z)} (dx', dy', dz') = (\Delta x, \Delta y, \Delta z)$$

For small $\vec{\Delta r}$ we have:

$$\vec{\nabla} \phi \cdot \vec{\Delta r} = -\vec{E}(\vec{r}) \cdot \vec{\Delta r}$$

This relation must hold for any (small) $\vec{\Delta r}$.

Let $\vec{\Delta r} = (\Delta x, 0, 0)$, displacement in x only.

$$\begin{aligned} \vec{\nabla} \phi \cdot \vec{\Delta r} &= \left(\frac{\partial \phi}{\partial x}, \frac{\partial \phi}{\partial y}, \frac{\partial \phi}{\partial z} \right) \cdot (\Delta x, 0, 0) = \frac{\partial \phi}{\partial x} \Delta x \\ &= -\vec{E} \cdot \vec{\Delta r} = -E_x \Delta x \end{aligned}$$

$$\Rightarrow E_x = -\frac{\partial \phi}{\partial x}$$

Similarly for other displacements:

$$\vec{\Delta r} = (0, \Delta y, 0) \Rightarrow E_y = -\frac{\partial \phi}{\partial y}$$

$$\vec{\Delta r} = (0, 0, \Delta z) \Rightarrow E_z = -\frac{\partial \phi}{\partial z}$$

So we have: $(E_x, E_y, E_z) = -\left(\frac{\partial \phi}{\partial x}, \frac{\partial \phi}{\partial y}, \frac{\partial \phi}{\partial z} \right)$

Or in vector form: $\boxed{\vec{E}(\vec{r}) = -\vec{\nabla} \phi(\vec{r})}$

example: point charge q .



Potential is $\phi(\vec{r}) = \frac{q}{4\pi\epsilon_0 r}$. Compute \vec{E} .

$$\vec{E} = -\vec{\nabla}\phi = -\frac{q}{4\pi\epsilon_0} \vec{\nabla}\left(\frac{1}{r}\right)$$

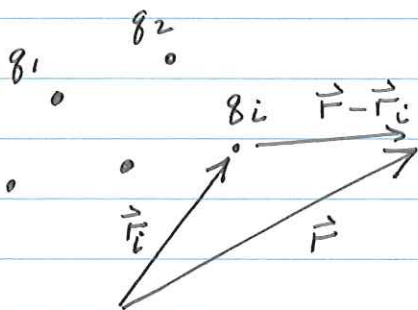
Note: we already computed

$$\frac{\partial}{\partial x}\left(\frac{1}{r}\right) = -\frac{x}{r^3}, \quad \frac{\partial}{\partial y}\left(\frac{1}{r}\right) = -\frac{y}{r^3}, \quad \frac{\partial}{\partial z}\left(\frac{1}{r}\right) = -\frac{z}{r^3}$$

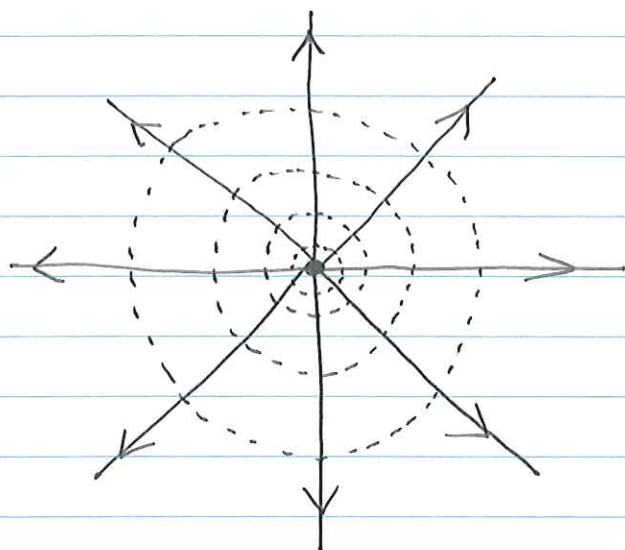
$$\begin{aligned} \text{Then } \vec{\nabla}\left(\frac{1}{r}\right) &= -\left(\frac{x}{r^3}, \frac{y}{r^3}, \frac{z}{r^3}\right) = -\frac{1}{r^3}(x, y, z) \\ &= -\frac{1}{r^3} \vec{r} = -\frac{\hat{r}}{r^2} \end{aligned}$$

$$\underline{\underline{\vec{E}(\vec{r}) = \frac{q}{4\pi\epsilon_0} \frac{\hat{r}}{r^2}}}$$

example: multiple point charges q_1, q_2, \dots, q_N at positions $\vec{r}_1, \vec{r}_2, \dots$. What is ϕ at \vec{r} ?



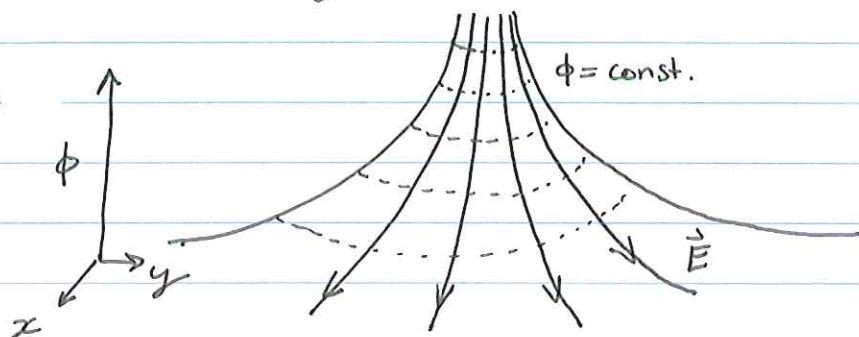
$$\phi(\vec{r}) = \sum_{i=1}^N \frac{q_i}{4\pi\epsilon_0 |\vec{r} - \vec{r}_i|}$$



Electric field lines from
point charge

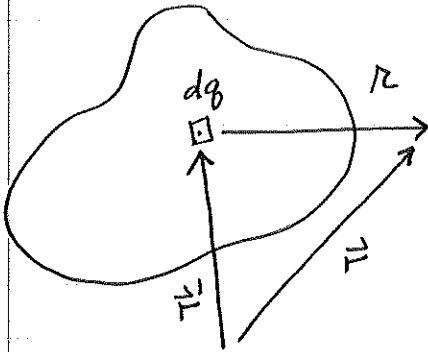
Lines of constant $\phi(\vec{r})$
= equipotentials

ϕ is like the height of ~~a~~ ^a hillside. ~~Equipotentials~~
Equipotentials are contours of constant height
along the hill.



$\vec{E} = -\vec{\nabla}\phi$ points down hill along steepest path, perpendicular
to equipotentials.

Potential for continuous charge distributions



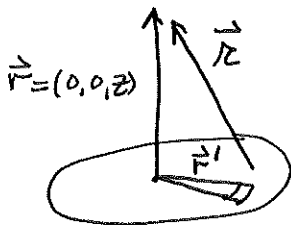
\vec{r}' = position of dq
 \vec{r} = where ϕ is measured
 $\vec{R} = \vec{r} - \vec{r}'$

$$\phi(\vec{r}) = \sum_{dq} \frac{dq}{4\pi\epsilon_0 R} \rightarrow \int \frac{dq}{4\pi\epsilon_0 R}$$

e.g. charge density $\rho \Rightarrow dq = \rho dV$

$$\phi(\vec{r}) = \frac{1}{4\pi\epsilon_0} \int dV \frac{\rho(\vec{r}')}{R} = \frac{1}{4\pi\epsilon_0} \int dV \frac{\rho(\vec{r}')}{|\vec{r} - \vec{r}'|}$$

example: charged disk of radius R and surface charge σ .
 what is potential ϕ at $\vec{r} = (0, 0, z)$



$$\vec{r}' = (x', y', 0)$$

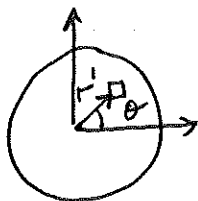
write in spherical coords

$$= (s \cos \theta, s \sin \theta, 0)$$

$$\vec{r} = (0, 0, z)$$

$$\vec{R} = (-s \cos \theta, -s \sin \theta, z)$$

$$R = (s^2 + z^2)^{1/2}$$



44a

$$\begin{aligned}\phi(\vec{r}) &= \frac{1}{4\pi\epsilon_0} \int \frac{dA}{r} = \frac{1}{4\pi\epsilon_0} \int \frac{\sigma s ds d\theta}{\sqrt{s^2+z^2}} \\ &= \frac{\sigma}{4\pi\epsilon_0} \int_0^R \frac{s ds}{\sqrt{s^2+z^2}} \int_0^{2\pi} d\theta \\ &= \frac{\sigma}{4\pi\epsilon_0} 2\pi \cdot (\sqrt{R^2+z^2} - z)\end{aligned}$$

$$\phi(z) = \frac{\sigma}{2\epsilon_0} (\sqrt{R^2+z^2} - z)$$

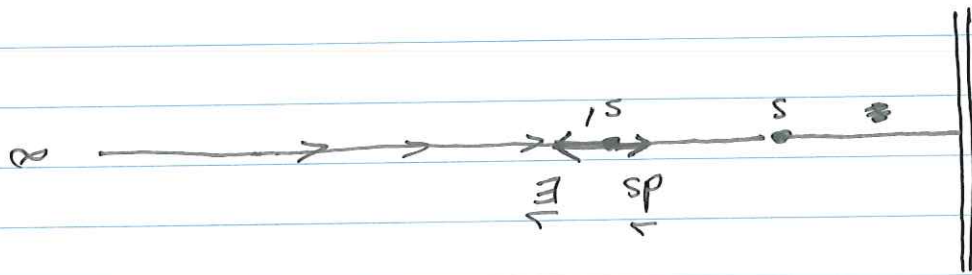
Check: $\vec{E} = -\vec{\nabla}\phi$

$$E_z = -\frac{\partial\phi}{\partial z} = \frac{\sigma}{2\epsilon_0} \left(1 - \frac{z}{\sqrt{z^2+R^2}}\right)$$

$E_x = E_y = 0$ by symmetry.

$$\Rightarrow \vec{E}(0,0,z) = \frac{\sigma}{2\epsilon_0} \left(1 - \frac{z}{\sqrt{z^2+R^2}}\right) \hat{z}$$

↑
Tutorial #2



Compute ϕ by integrating along \hat{s} direction

$$\vec{E} = \frac{\lambda}{s} \hat{s}$$

Compute ϕ from line integral of \vec{E} :

We get $\phi(s) = \infty$. What went wrong here?

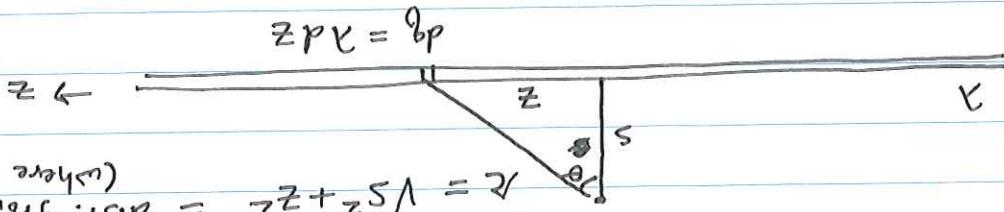
$$\phi = \frac{\lambda}{4\pi\epsilon_0} \int_{\frac{z}{2}}^{\frac{z}{2}} \frac{\sec^2\theta}{\sec\theta} d\theta = \frac{\lambda}{4\pi\epsilon_0} \int_{\pi/2}^{-\pi/2} d\theta \sec\theta = \infty$$

$$z = \pm\infty \rightarrow \theta = \pm\frac{\pi}{2}$$

$$dz = s \sec^2\theta d\theta$$

Trig. substitution: $z = s \tan\theta$

$$\phi = \int_{-\infty}^{\infty} \frac{dq}{dg} = \int_{-\infty}^{\infty} \frac{\lambda dz}{\lambda \sqrt{s^2 + z^2}}$$



$$r = \sqrt{s^2 + z^2} = \text{dist. from } dq \text{ to } \vec{r}$$

(where ϕ is measured)

Example: infinite wire. Find ϕ a distance s from wire.

s' is position along path from ∞ to final position s . $\vec{ds} = ds' \hat{s}$

$$\phi(s) = - \int_{\infty}^s ds' \hat{s} \cdot \vec{E}(s') = - \int_{\infty}^s ds' \frac{\lambda}{2\pi\epsilon_0 s'}$$

$$= \frac{\lambda}{2\pi\epsilon_0} \int_s^{\infty} ds' \frac{1}{s'} = \frac{\lambda}{2\pi\epsilon_0} \ln s' \Big|_{s'=s}^{s'=\infty} = \infty$$

Because we defined the potential with respect to position $\vec{r}_0 \rightarrow \infty$, we got $\phi = \infty$.

For infinite charge distributions, it takes an infinite amount of work to bring in a test charge q_0 from ∞ .

Still can define potential, but with respect to a finite \vec{r}_0 .

e.g. Suppose \vec{r}_0 is a distance s_0 from the wire, then

$$\phi(s) = \frac{\lambda}{2\pi\epsilon_0} \ln s' \Big|_s^{s_0} = \frac{\lambda}{2\pi\epsilon_0} \ln(s_0/s)$$

For a finite charge distribution (ie. localized within some finite volume), can define ϕ with respect to $\vec{r}_0 \rightarrow \infty$.

Note: \vec{E} doesn't depend on \vec{r}_0 .

In Cartesian coords: $s = \sqrt{x^2 + y^2}$

$$\begin{aligned} \text{So } \phi(x, y, z) &= \frac{\lambda}{2\pi\epsilon_0} \ln\left(\frac{s_0}{\sqrt{x^2 + y^2}}\right) \\ &= \frac{\lambda}{2\pi\epsilon_0} \left(\ln s_0 - \frac{1}{2} \ln(x^2 + y^2) \right) \end{aligned}$$

Then

$$\begin{aligned} \vec{E} &= -\vec{\nabla}\phi = -\left(\frac{\partial\phi}{\partial x}, \frac{\partial\phi}{\partial y}, 0\right) \\ &= \frac{\lambda}{4\pi\epsilon_0} \frac{1}{x^2 + y^2} (2x, 2y, 0) \\ &= \frac{\lambda}{2\pi\epsilon_0 s} \left(\frac{x}{s}, \frac{y}{s}, 0\right) = \frac{\lambda}{2\pi\epsilon_0 s} \hat{s} \\ &\qquad\qquad\qquad \hat{s} = \frac{x}{s} \hat{x} + \frac{y}{s} \hat{y} \end{aligned}$$

Here we computed gradient $\vec{\nabla}\phi$ by converting to Cartesian coordinates (x, y, z) since $\vec{\nabla} = \left(\frac{\partial}{\partial x}, \frac{\partial}{\partial y}, \frac{\partial}{\partial z}\right) = \frac{\partial}{\partial x} \hat{x} + \frac{\partial}{\partial y} \hat{y} + \frac{\partial}{\partial z} \hat{z}$

But you can also express $\vec{\nabla}$ in cylindrical or spherical coords as well.

First, recall the chain rule:

Suppose you have a function $f(y)$, but y depends on x according to $y(x)$.

You can express f as a function of x as:

$$f(y(x))$$

What is the derivative with respect to x ?

$$\frac{df}{dx} = \frac{d}{dx} f(y(x)) = f'(y(x)) \cdot y'(x)$$

$$\frac{df}{dx} = \frac{df}{dy} \cdot \frac{dy}{dx}$$

Now, suppose $\phi = \phi(s, z)$ only depends on s, z in cylindrical coords. Treat $s = s(x, y) = \sqrt{x^2 + y^2}$ as a function of x, y .

$$\vec{\nabla} \phi(s, z) = \vec{\nabla} \phi(s(x, y), z)$$

$$= \left(\frac{\partial \phi}{\partial x}, \frac{\partial \phi}{\partial y}, \frac{\partial \phi}{\partial z} \right)$$

$$= \left(\frac{\partial \phi}{\partial s} \frac{\partial s}{\partial x}, \frac{\partial \phi}{\partial s} \frac{\partial s}{\partial y}, \frac{\partial \phi}{\partial z} \right) \quad \text{chain rule}$$

$$= \left(\frac{x}{s} \frac{\partial \phi}{\partial s}, \frac{y}{s} \frac{\partial \phi}{\partial s}, \frac{\partial \phi}{\partial z} \right)$$

$$= \frac{\partial \phi}{\partial s} \underbrace{\left(\frac{x}{s} \hat{x} + \frac{y}{s} \hat{y} \right)}_{\hat{s}} + \frac{\partial \phi}{\partial z} \hat{z}$$

$$\text{So } \vec{\nabla} \phi(s, z) = \frac{\partial \phi}{\partial s} \hat{s} + \frac{\partial \phi}{\partial z} \hat{z}$$

$$\boxed{\vec{\nabla} = \frac{\partial}{\partial s} \hat{s} + \frac{\partial}{\partial z} \hat{z}}$$

Infinite wire example:

$$\begin{aligned} \vec{E} &= -\vec{\nabla} \left(\frac{\lambda}{2\pi\epsilon_0} \ln(s_0/s) \right) = -\frac{\partial}{\partial s} \left(\frac{\lambda}{2\pi\epsilon_0} \ln(s_0/s) \right) \hat{s} \\ &= \frac{\lambda}{2\pi\epsilon_0 s} \hat{s} \end{aligned}$$

Spherical coordinates: assume ϕ only depends on $r = r(x, y, z) = \sqrt{x^2 + y^2 + z^2}$.

Also recall $\hat{r} = \left(\frac{x}{r}, \frac{y}{r}, \frac{z}{r} \right)$.

$$\begin{aligned} \vec{\nabla} \phi(r) &= \left(\frac{\partial \phi}{\partial r} \frac{\partial r}{\partial x}, \frac{\partial \phi}{\partial r} \frac{\partial r}{\partial y}, \frac{\partial \phi}{\partial r} \frac{\partial r}{\partial z} \right) \\ &= \frac{\partial \phi}{\partial r} \left(\frac{x}{r}, \frac{y}{r}, \frac{z}{r} \right) = \frac{\partial \phi}{\partial r} \hat{r} \end{aligned}$$

So $\vec{\nabla} = \frac{\partial}{\partial r} \hat{r}$

Gradient:

Cartesian $\vec{\nabla} = \frac{\partial}{\partial x} \hat{x} + \frac{\partial}{\partial y} \hat{y} + \frac{\partial}{\partial z} \hat{z}$

Cylindrical $\vec{\nabla} = \frac{\partial}{\partial s} \hat{s} + \frac{\partial}{\partial z} \hat{z}$

Spherical $\vec{\nabla} = \frac{\partial}{\partial r} \hat{r}$

} only valid when ϕ doesn't depend on angles θ or (θ, ϕ) otherwise more complicated.

example: point charge $\phi(r) = \frac{q}{4\pi\epsilon_0 r}$

$$\vec{E} = -\vec{\nabla}\phi = -\hat{r} \frac{\partial\phi}{\partial r} = \frac{q}{4\pi\epsilon_0 r^2} \hat{r}$$

Electric dipole moments & multipole expansion

Any finite charge distribution with total charge Q and typical size R (e.g. ring of radius R) behaves like a point charge Q sufficiently far away ($r \gg R$): $\phi(r) = \frac{Q}{4\pi\epsilon_0 r}$ for $r \gg R$.

This idea can be generalized using multipole expansion

$\phi(r) = \frac{Q}{4\pi\epsilon_0 r}$ is called the monopole term.

Depends on total charge Q and falls as ~~$1/r^2$~~ $1/r$.

Consider a ^{configuration} ~~case~~ where $Q=0$.

Two charges $+q$ and $-q$ separated by distance d .

Find $\phi(\vec{r})$ for $r \gg d$.

