## PHYS 3090: Homework 2 (due Friday Sept. 26)

1. Consider the matrix  $M = \begin{pmatrix} \cos \theta \, e^{i\alpha} & \sin \theta \, e^{i\beta} \\ \sin \theta \, e^{i\phi} & \cos \theta \, e^{i\eta} \end{pmatrix}$ .

- What are the conditions on the phases  $(\alpha, \beta, \phi, \eta)$  such that M is Hermitian for any value of  $\theta$ ?
- What are the conditions on the phases  $(\alpha, \beta, \phi, \eta)$  such that M is unitary for any value of  $\theta$ ?

2. Consider a double-spring system, with equal masses m and spring constants k and  $\frac{3}{2}k$ , where  $x_1$  and  $x_2$  measure the displacements from the equilibrium (see Figure 1 left).

- What is the potential energy V?
- Determine the normal frequencies and the normal modes.
- Suppose at t = 0, the system had the initial condition

$$x_1(0) = 0, \quad x_2 = d, \quad \dot{x}_1(0) = \dot{x}_2(0) = 0.$$
 (1)

Using eigenvalue methods, determine  $\vec{x}(t)$  for t > 0.

• Compute the linear momentum  $p_1$  and  $p_2$  of each of the two masses as a function of t.

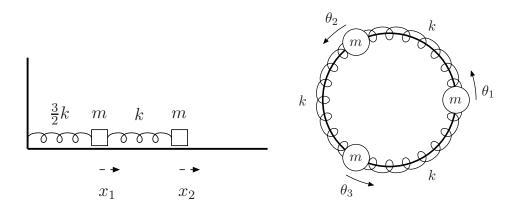


Figure 1: Left: Double spring system with spring constants k and  $\frac{3}{2}k$  and masses m on a frictionless surface. Right: three masses m connected by springs in a ring configuration.

3. Consider circular configuration of three masses shown in Figure 1 (right). All three masses (with mass m) and all three springs (with spring constant k) are fixed to move along the circle of radius R. Let the variables  $(\theta_1, \theta_2, \theta_2)$  be the angular displacements of each mass from its equilibrium position.

- What is the potential energy V in terms of k, R, and  $\theta_i$ ?
- Write the equation of motion for this system as  $\ddot{\vec{\theta}} = -U\vec{\theta}$ , where  $\vec{\theta} = \begin{pmatrix} \theta_1 \\ \theta_2 \\ \theta_3 \end{pmatrix}$  and U is a 3 × 3 matrix.

What is U in terms of k, m, and R?

- What are the normal frequencies and normal modes for this system?
- Suppose at time t = 0 all masses begin at their equilibrium positions and we give mass 1 a "kick" so that it has velocity v (and the other masses begin at rest). This corresponds to an initial condition:

$$\theta_1(0) = \theta_2(0) = \theta_3(0) = 0, \qquad R\dot{\theta}_1(0) = v, \quad \dot{\theta}_2(0) = \dot{\theta}_3(0) = 0.$$
 (2)

Using eigenvalue methods, determine  $\vec{\theta}(t)$  for t > 0.

• Compute the angular momentum  $L_1$ ,  $L_2$ , and  $L_3$  for each of the three masses as a function of t. Show that the total angular momentum  $L_1 + L_2 + L_3$  is constant in time.