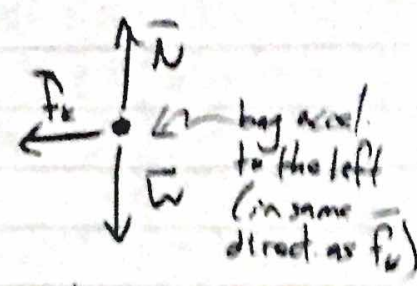


P1 Assume (kinetic) friction force is the key force acting on the bag to accelerate it from  $v_0 = 0$  to  $v_f = 2.0 \text{ m/s}$  (at which point bag stops moving re the conveyor belt)



$$|f_k| = \mu_k |N| = \mu_k mg = 0.3(10)(9.8) \approx 29.4 \text{ N} \quad \leftarrow$$

$$(F_{\text{net}})_x = \sum F_x = f_k = ma = 10.0a \Rightarrow a = 2.94 \text{ m/s}^2$$

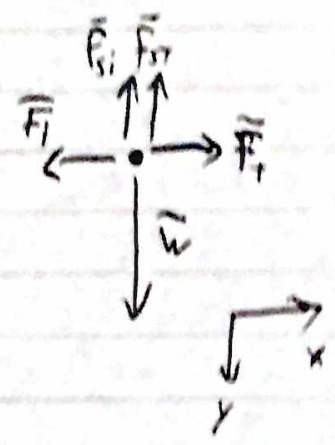
(this is the const. accel. the bag experiences)

$$v_f^2 = v_0^2 + 2a(x_f - x_0) = 0 + 2(2.94)(x_f - 0) = 2.0^2$$

$$\Rightarrow x_f = \frac{4.0}{2(2.94)} \approx 0.68 \text{ m} = x_f$$

Note: Static friction didn't directly come into play. Why?

P2 Let  $\vec{F}_r$  be force from thumb and  $\vec{F}_i$  be from index finger.  $|\vec{F}_i| = |\vec{F}_r| = 6.0 \text{ N}$  (because book is at equilibrium)



book will start to slip when  $|\vec{W}| = \mu_s |\vec{F}_r| + \mu_s |\vec{F}_i|$

$$\text{So } |\vec{W}| = 2\mu_s(6.0) = 2(0.8)(6.0) \approx 9.6 \text{ N}$$

$\Rightarrow$  So the heaviest book would be  $\approx 9.6 \text{ N}$