

### The permutation group $S_3$

Consider the permutations of 3 objects. There are  $3! = 6$  permutations. We can label a permutation by its action on a set of objects  $\{O_1, O_2, O_3\}$  to locations  $\{L_1, L_2, L_3\}$ .

For example, the permutation  $(2, 3, 1)$  corresponds to moving object  $O_2$  to  $L_1$ ,  $O_3$  to  $L_2$  and  $O_1$  to  $L_3$ .

So the set of permutations are:

$$\begin{aligned} e &\equiv (1, 2, 3) \\ a &\equiv (2, 3, 1) \\ b &\equiv (3, 1, 2) \\ x &\equiv (1, 3, 2) \\ y &\equiv (3, 2, 1) \\ z &\equiv (2, 1, 3) \end{aligned}$$

The group multiplication table is:

	$e$	$a$	$b$	$x$	$y$	$z$
$e$	$e$	$a$	$b$	$x$	$y$	$z$
$a$	$a$	$b$	$e$	$z$	$x$	$y$
$b$	$b$	$e$	$a$	$y$	$z$	$x$
$x$	$x$	$y$	$z$	$e$	$a$	$b$
$y$	$y$	$z$	$x$	$b$	$e$	$a$
$z$	$z$	$x$	$y$	$a$	$b$	$e$

Alternatively, one can think in terms of rotations  $\{a, b\}$  and reflections  $\{x, y, z\}$  of an equilateral triangle.

We see that the set  $\{e, a, b\}$  forms a subgroup. We see that this subgroup is the same as  $Z_3$ . Groups with different physical origin, and yet the same group structure are isomorphic.

A two dimensional irreducible representation of  $S_3$  is:

$$D(e) = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}, \quad D(a) = \begin{pmatrix} -\frac{1}{2} & -\frac{\sqrt{3}}{2} \\ \frac{\sqrt{3}}{2} & -\frac{1}{2} \end{pmatrix}, \quad D(b) = \begin{pmatrix} -\frac{1}{2} & \frac{\sqrt{3}}{2} \\ -\frac{\sqrt{3}}{2} & -\frac{1}{2} \end{pmatrix}$$

$$D(z) = \begin{pmatrix} -1 & 0 \\ 0 & 1 \end{pmatrix}, \quad D(x) = \begin{pmatrix} \frac{1}{2} & \frac{\sqrt{3}}{2} \\ \frac{\sqrt{3}}{2} & -\frac{1}{2} \end{pmatrix}, \quad D(y) = \begin{pmatrix} \frac{1}{2} & -\frac{\sqrt{3}}{2} \\ -\frac{\sqrt{3}}{2} & -\frac{1}{2} \end{pmatrix}$$

It is interesting that this irreducible representation is more than 1 dimensional. It is necessary that at least some of the representations of a non-Abelian group must be matrices rather than numbers. Only matrices can reproduce the non-Abelian multiplication laws.

Here's a 3 dimensional representation of  $S_3$

$$D(e) = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}, \quad D(a) = \begin{pmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 1 & 0 & 0 \end{pmatrix}, \quad D(b) = \begin{pmatrix} 0 & 0 & 1 \\ 1 & 0 & 0 \\ 0 & 1 & 0 \end{pmatrix}$$

$$D(z) = \begin{pmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 1 \end{pmatrix}, \quad D(x) = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 1 & 0 \end{pmatrix}, \quad D(y) = \begin{pmatrix} 0 & 0 & 1 \\ 0 & 1 & 0 \\ 1 & 0 & 0 \end{pmatrix}$$

This particular representation is important because it is the defining representation for the group - it actually implements the permutations on the states.

$$\begin{aligned} D_3(a)|1\rangle &= \sum_k |k\rangle [D_3(a)]_{k1} = |3\rangle \\ D_3(a)|2\rangle &= \sum_k |k\rangle [D_3(a)]_{k2} = |1\rangle \\ D_3(a)|3\rangle &= \sum_k |k\rangle [D_3(a)]_{k3} = |2\rangle \end{aligned}$$

This 3 dimensional representation decomposes into a direct sum of the irreducible representations,

$$D_3 = D_1 \oplus D_2$$