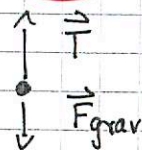


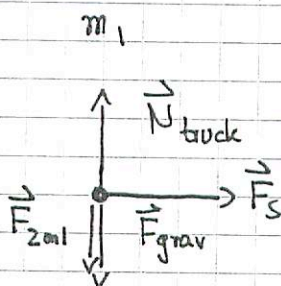
Phys 141C : class test # 2

- ① tension is greatest at lowest point, (0.5)
 because it has to compensate gravity ($T = m(g + \frac{v^2}{R})$
 in this case) (0.5)

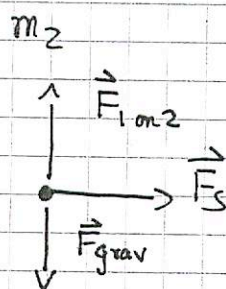
(optional: FBD for lowest point
 require $ma_c = T - mg$)



- ② a)



(1)



(1)

- b) Consider Newton-2 for horizontal + vertical components;
 start with m_2 :

$$\hat{i}: m_2 a = F_s^{(2)} = (16 \times 1.5) \text{ kg} \cdot \frac{\text{m}}{\text{s}^2} = 24 \text{ N} \quad (0.5)$$

$$\hat{j}: 0 = F_{1on2} - m_2 g \quad (0.5)$$

$$\Leftrightarrow F_{1on2} = m_2 g = 160 \text{ N} \quad (0.5)$$

$$m_1: \hat{i}: m_1 a = F_s^{(1)} = (32 \times 1.5) \text{ kg} \cdot \frac{\text{m}}{\text{s}^2} = 48 \text{ N} \quad (0.5)$$

$$\hat{j}: 0 = -m_1 g + N_{\text{truck}} + \overbrace{F_{2on1}}^{<0} \quad (0.5)$$

$$\Leftrightarrow N_{\text{truck}} = m_1 g + F_{1on2} \quad (\text{use Newton-3}) \quad (0.5)$$

$$= 470 \text{ N} \quad ; \quad m_1 g = 310 \text{ N} \quad (0.5)$$

③

$$a) \quad \vec{r}(t) = R \cos \omega t \hat{i} + R \sin \omega t \hat{j}$$

$$\vec{v}(t) = \frac{d\vec{r}}{dt} = -R\omega \sin \omega t \hat{i} + R\omega \cos \omega t \hat{j} \quad (0.5)$$

$$\vec{a}(t) = \frac{d\vec{v}}{dt} = -R\omega^2 \cos \omega t \hat{i} - R\omega^2 \sin \omega t \hat{j} \quad (0.5)$$

$$= -\omega^2 (R \cos \omega t \hat{i} + R \sin \omega t \hat{j}) \quad (0.5)$$

$$= -\omega^2 \vec{r}(t) \quad (0.5)$$

$$a_c = |\vec{a}(t)| = \omega^2 |\vec{r}(t)| = \omega^2 R \quad (0.5)$$

$$= \left(\frac{v}{R}\right)^2 R = \frac{v^2}{R} \quad (0.5)$$

use $v = |\vec{v}| = \omega R$

$$b) \quad F_{\text{grav}} = \frac{GM_E M_0}{d_{SE}^2} = M_E a_c = M_E \frac{v^2}{R_{SE}} \quad (1)$$

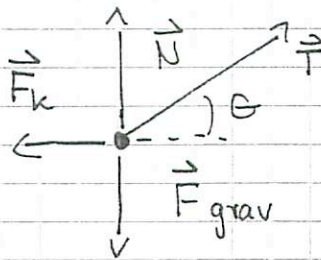
$$\Leftrightarrow v^2 = \frac{GM_0}{d_{SE}} = \left(8.9 \times 10^8 \left(\frac{m}{s}\right)^2\right) \quad (0.5)$$

$$v = \sqrt{\frac{GM_0}{d_{SE}}} = 3.0 \times 10^4 \text{ m/s} \quad (0.5)$$

4

(a)

FBD



(1)

$$(b) \quad \hat{i}: \quad m a_x = F_{\text{net},x} = -|F_k| + T \cos \theta \quad (0.5)$$

$$\hat{j}: \quad 0 = m a_y = F_{\text{net},y} = N + T \sin \theta - m g \quad (0.5)$$

$$\Leftrightarrow N = m g - T \sin \theta \quad (0.5)$$

use it to determine $|F_k| = \mu_k N$

$$= \mu_k (m g - T \sin \theta) \quad (0.5)$$

$$\text{summary:} \quad F_{\text{net},x} = -\mu_k (m g - T \sin \theta) + T \cos \theta$$

$$= -\mu_k m g + T (\mu_k \sin \theta + \cos \theta)$$

$$= -35.8 + 35 \times 1.08$$

$$= 2.0 \text{ N} \quad (0.5)$$

$$F_{\text{net},y} = 0 \quad (0.5)$$

$$(c) \quad W_{\text{rope}} = \vec{T} \cdot \Delta \vec{r} = T \Delta x \cos \theta = 220 \text{ J} \quad (1)$$

$$(d) \quad W_{\text{fric}} = \vec{F}_k \cdot \Delta \vec{r} = -F_k \Delta x = -200 \text{ J} \quad (1)$$

$$(e) \quad W_{\text{net}} = \vec{F}_{\text{net}} \cdot \Delta \vec{r} = F_{\text{net},x} \cdot \Delta x = 14 \text{ J} \quad (1)$$

$$(f) \quad \text{Work-energy theorem:} \quad \Delta KE = W_{\text{net}}$$

$$\Leftrightarrow KE_f = KE_i + W_{\text{net}}$$

$$= \frac{m}{2} v_i^2 + W_{\text{net}} = 18 \text{ J} \quad (1)$$