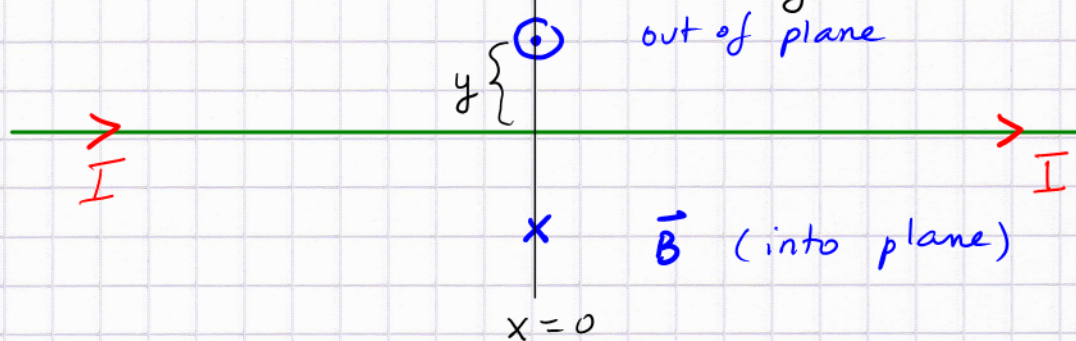


# Biot-Savart: obtaining the $\vec{B}$ field for a current c16 W10

Objective: given a straight, very long (infinite) wire with an electric current  $\rightarrow$  obtain the B field strength as a function of the distance from the wire

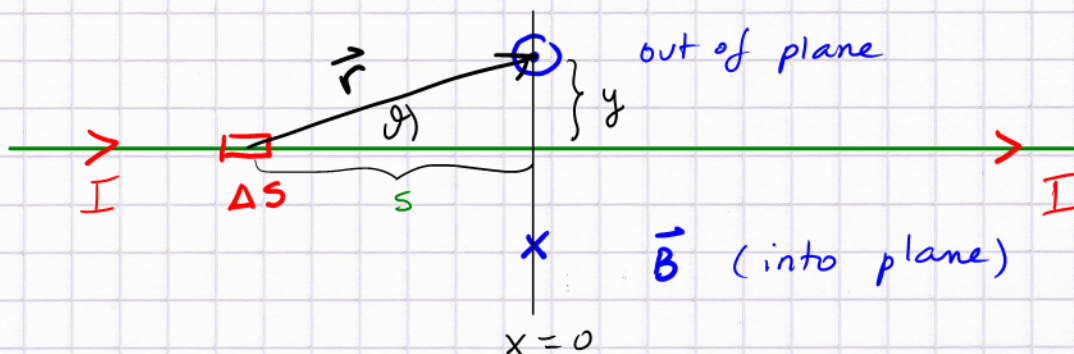


Start with some symmetries.

1) The  $\vec{B}$  field lines are circles surrounding the wire  $\therefore B_x = 0, B_y = 0$ , only  $B_z \neq 0$  for the x-y plane locations

2) we need to calculate only for  $x=0$ : for an  $\infty$ -ly long wire there should be no x-dependence of  $B_z(x, y) \therefore$  only  $B_z(y)$  to be determined

3)  $\vec{B} = \frac{\mu_0}{4\pi} I \frac{(\Delta\vec{s} \times \hat{r})}{r^2}$  requires us to chop the wire into small segments  $\Delta\vec{s} = \hat{L} \Delta s$  and sum contributions



contribution from  $\Delta s$  at  $(x=0, y)$ :

$$\Delta B = \frac{\mu_0}{4\pi} I \frac{\Delta s \cdot \sin\theta}{r^2} = \frac{\mu_0}{4\pi} I \frac{\Delta s y}{r^3} = \frac{\mu_0}{4\pi} I \frac{\Delta s y}{(s^2 + y^2)^{3/2}}$$

Remarks, before we proceed to sum all  $\Delta B$ :

(2)

- we expect the biggest contribution from  $s=0$ , since the denominator  $\sim s^3$  (for small distance  $y$  from the wire)
- the Biot-Savart law is a "cousin" to Coulomb's law it has a  $\frac{1}{r^2}$  fall-off built in, but is more complicated, as the current direction matters. However, if the point where we are calculating the  $\vec{B}$  field ( $x=0, y, z=0$ ) was co-moving with the charge travelling inside the wire, then we would calculate an electric  $\vec{E}$  field from static charge segments.  $\vec{E}$  and  $\vec{B}$  somehow transform into each other when changing reference frames  $\rightarrow$  understand in upper-year courses!

Total B field  $B_z(x=0, y, z=0)$ :

$$B_z = \sum \Delta B = \frac{\mu_0}{4\pi} I \int_{-\infty}^{\infty} \frac{y ds}{(s^2 + y^2)^{3/2}}$$

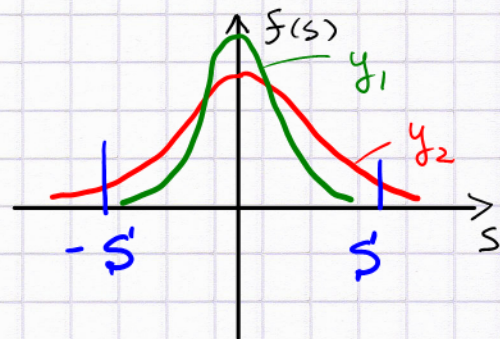
area under a bell-shaped curve which depends on the value of  $y$

Calculating this area involves a double limit:

1) finite  $s'$ :  $\int_{-s'}^{s'} \frac{y ds}{(s^2 + y^2)^{3/2}}$

2) then  $\lim_{s' \rightarrow \infty}$

together: "improper integral"  $\rightarrow$



anti-derivative of  $\frac{1}{(x^2 + a^2)^{3/2}}$  is  $\frac{x}{a^2 \sqrt{x^2 + a^2}}$

$$\therefore y \int_{-s'}^{s'} \frac{ds}{(s^2 + y^2)^{3/2}} = y \left[ \frac{s}{y^2 \sqrt{s^2 + y^2}} - \frac{-s}{y^2 \sqrt{s^2 + y^2}} \right]$$

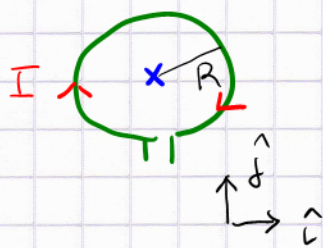
$$= \frac{2s'}{y \sqrt{s'^2 + y^2}} \xrightarrow{s' \rightarrow \infty} \frac{2}{y}$$

$$\therefore \boxed{B_z(y) = \frac{\mu_0}{4\pi} I \cdot \frac{2}{y}} \quad \text{at } x=0, z=0$$

(3)

Main result: a long, current-carrying wire surrounds itself with a  $\vec{B}$  field, the field lines form circles, with direction given by the RH rule and a strength given by  $\frac{\mu_0}{2\pi} I \left(\frac{1}{d}\right)$  where  $d$  is the perpendicular distance from the wire.

Analogous calculation for a loop of wire (radius  $R$ ) leads to a formula for the field strength at the centre of the loop



$B_{z, \text{centre}} < 0$   
(into the plane)  
by RH rule

$$|B_z| = \frac{\mu_0}{2} \frac{I}{R}$$

For an  $N$ -turn coil (coil means: length  $\ll$  radius  $R$ ):

$$|B_{z, \text{centre}}| = \frac{\mu_0}{2} \frac{N \cdot I}{R}$$

This is a practical result. Note: this is for an empty coil (no "soft-iron" core). An iron core can be used to strengthen the field. (iron is magnetized, but not permanently)

Units: B-field SI unit: Tesla =  $\frac{1 \text{ N}}{\text{A m}}$

$$\mu_0 \equiv 4\pi \times 10^{-7} \frac{\text{T m}}{\text{A}} = 1.257 \times 10^{-6} \frac{\text{T m}}{\text{A}}$$

Example: coil of radius  $R=0.1 \text{ m}$ , current  $1.0 \text{ A}$ , one turn ( $N=1$ )

$$B_{\text{centre}} = \frac{\mu_0}{2} \frac{I}{R} = \frac{1.26 \times 10^{-6}}{2} \frac{1.0}{0.1} \frac{\text{T m}}{\text{A}} \frac{\text{A}}{\text{m}} = 6.5 \times 10^{-6} \text{ T}$$

The earth's magnetic field at our latitude and @ surface ④  
 $\sim 50 \mu\text{T} = 5.0 \times 10^{-5} \text{T}$

Thus, our simple current loop is weaker than  
the earth's magnetic field

$\Rightarrow$  in practice: use more turns

Solenoid vs coil: if the windings are put together such  
that the length of the electromagnet  $L > R$ , we call it  
a solenoid. A different calculation is needed, usually  
based on Ampère's law. (section 20.7)

On p. 665:

$$B_{\text{sol.}} = \frac{\mu_0 N I}{L}$$

A very similar formula, but the diameter  $2R$  is replaced  
by the length  $L$ . Very puzzling!

A more realistic calculation would reveal that the  
true answer should depend on both  $R$  and  $L$ ,  
perhaps replacing  $2R$  and  $L$  by  $\sqrt{L^2 + 4R^2}$   
such that the limits  $R \ll L$  and  $R \gg L$  are  
both recovered.

