

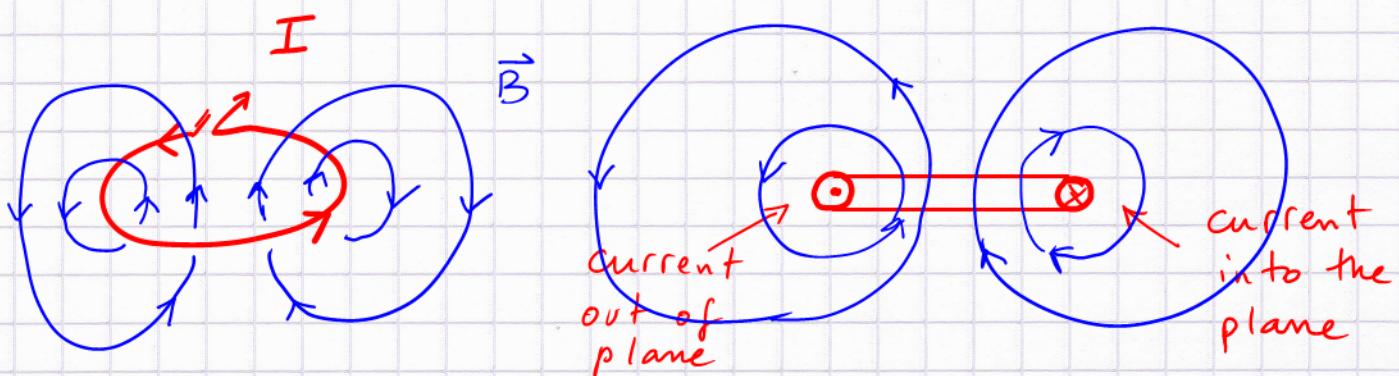
Magnetic Dipole: current loop or bar magnet

Biot - Savart allowed us to calculate from first principles :

- $\vec{B}$  - field around long straight wire
- $\vec{B}$  - field at centre of a current loop

For arbitrary positions in space the calculation is hard, and does not lead to a simple result.

∴ qualitative discussion :

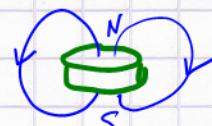


The  $\vec{B}$  field is not uniform in space  
(distance between field lines doesn't remain constant)

The field lines remind us of the earth's  $\vec{B}$  field  
(when drawn for the entire globe)

[origin of earth's  $\vec{B}$  : current loop in molten core]

Same  $\vec{B}$  field is obtained for a short permanent magnet



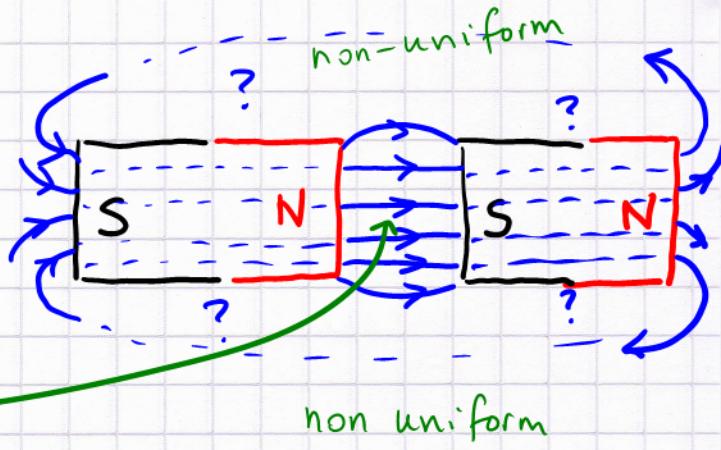
While we can't tell what's going on inside : we assume that the field lines are also closed loops in this case!

Q: We like homogeneous (uniform) fields.

Can we generate those?

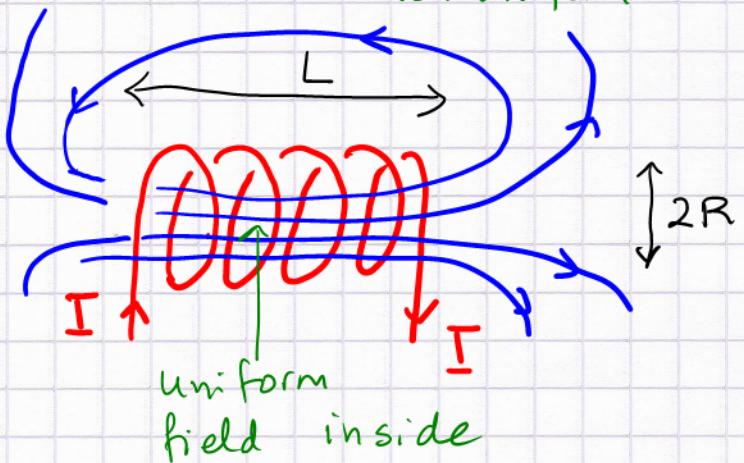
A: with permanent magnets  
of large cross section:

uniform  
field there!



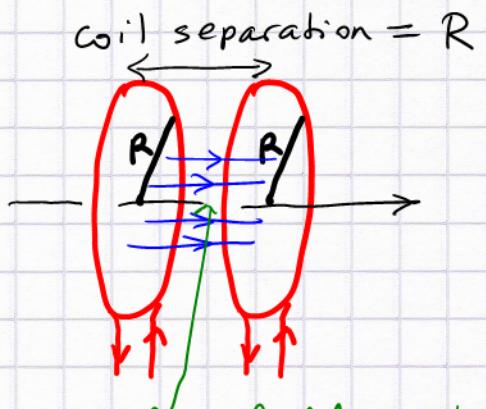
B: With electromagnets:

1) stacking current loops  
into a solenoid  
(not a coil):  $L \gg R$



2) Helmholtz coil  
arrangement

large- $R$  coils, many  
turns but length  $L \ll R$



uniform field in between

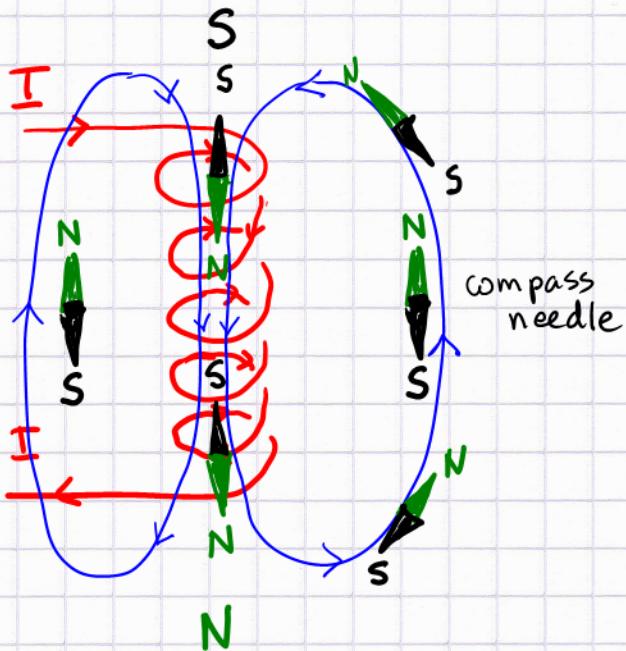
Q: How do we probe magnetic fields?

1) Compass needle aligns to be tangential to  $\vec{B}$   
= magnetic dipole

NB: the N-S orientation of the dipole  
aligns with the field direction

Q: so why does it appear to be opposite?

A: because we are usually observing it not inside the current loop, but outside!



A compass needle is a magnetic dipole.

In a magnetic field  $\vec{B}$   
it experiences a restoring  
torque which is zero  
when it is aligned.

When it is counteraligned, theoretically

the torque is also zero, but this orientation  
is unstable!



floating  
magnet?



fixed  
magnet

Will a counter-aligned set-up remain  
stable? (floating magnet due to  
repulsion)

NO: it will flip around and attract, unless it  
is prevented from doing so by a guide.

(e.g., ring magnets stacked on a post)

Before we understand this in detail, i.e., magnet-magnet interactions, or current-current interactions, we need to investigate how moving charges respond to the presence of a magnetic field!

## Magnetic force (Lorentz force)

Given a uniform (homogeneous) magnetic field  $\vec{B}$ .

A moving charge ( $q, \vec{v}$ ) experiences a deflection at right angles to both  $\vec{v}$  and  $\vec{B}$ :

$$\vec{F}_M = q(\vec{v} \times \vec{B}) \quad \begin{array}{l} \text{direction by full} \\ \text{RH rule +} \\ \text{charge sign} \end{array}$$

$$F_M = q|\vec{v}| |\vec{B}| \sin \theta \quad \theta = \angle \vec{v}, \vec{B}$$

$\nwarrow \quad \nearrow$   
can cause sign change, thus use

RH rule and

$$|F_M| = |qvB \sin \theta|$$

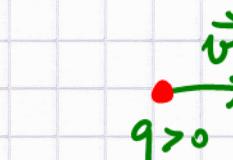
Example:

region with uniform  $\vec{B}$  into the plane

$\times \quad \times \quad \times \quad \times \quad \times$  (tails of  $\vec{B}$

$\times \quad \times \quad \times \quad \times \quad \times$  arrows are indicated)

$$\vec{B} = -B_0 \hat{k}$$



positive  
charge moves  
into the region



which way is the particle deflected?

$$\vec{v} = v_0 \hat{i}$$

$$\vec{B} = -B_0 \hat{k}$$

$$\vec{F}_M = qv_0 B_0 \hat{j}$$

also via determinant:

$$q \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ v_0 & 0 & 0 \\ 0 & 0 & -B_0 \end{vmatrix} =$$

RH rule:

thumb : points right  
index : points into plane  
middle = up!

$q > 0 \rightarrow \hat{j}$   
no change